Operator's manual Single row potato harvester

Model UN 5300 with options

UH124053



Guarantee

Kverneland product's are guaranteed for a period of one year from the date of delivery, against defects in material and workmanship.

Component's not manufactured by Kverneland, i.e. electrics and hydraulics, p.t.o. shafts and tyres are guaranteed according to the original manufacturer's recommendation.

The components listed below have limited guarantee due to their function.

Tyres

Pre-stretcher rollers

Webs

Knives

Light bulbs

Fuses

Safety clutches

Oil filter

Hydraulic seals for pumps, motors, valves and cylinders

Weakening due to wear and tear is concidered to be normal for these parts. The product guarantee for these components is limited to manufacturing defects, breakage, poor workmanship, transport damage etc on new machines.

If a failure is expected to be covered under the guarantee, the owner or its representative should inform the dealer when parts and/or repair work is required. Any guaranty claim should be applied for within the period of guarantee.

The dealer should fill in one guarantee claim form for each matter and forward it to the Kverneland sales company or importer before the 10th of the following month after the claim was raised.

The damaged parts should be marked with the number of the corresponding warranty claim and should be stored for 6 months by the dealer, available for inspection by the Kverneland sales company or importer if required.

Due to the operation of the Kverneland products being out of the manufacturer's control, the guarantee covers the product quality only. Performance or any consequential losses are not covered.

The guarantee may be invalid if:-

- a) spurious spare parts are used or the product is repaired or modified without the Kverneland authorization.
- b) operators and service instructions given by the manufacturer are not complied with.
- c) The machine is used for other purposes than those designed for.

The guarantee does not cover damage caused by normal wear.

Public safety regulations require from the manufacturer of this machine that all safety aspects regarding the use of the machine is thoroughly evaluated. As a result of these obligations Kverneland and its importer or sales company are not responsible for the function of components not shown in the spare parts catalogue covering this product.

Kverneland reserve the right to change the product with no obligation to previously supplied machines.

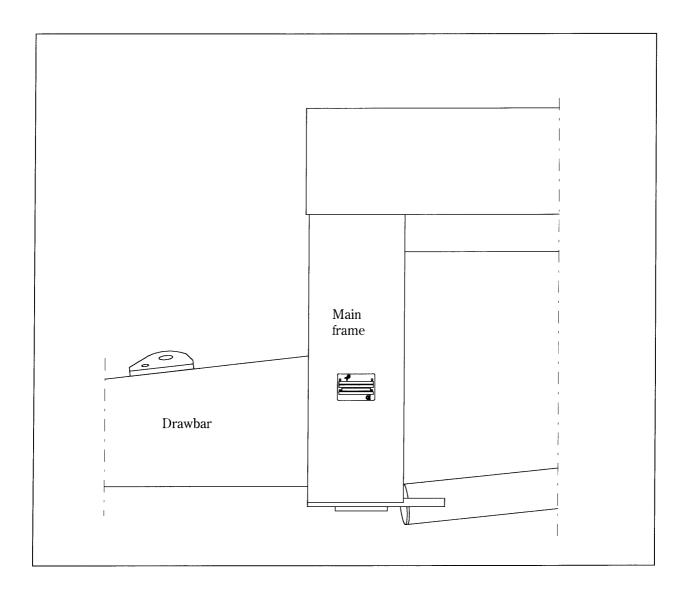


Machine identification

The machine's serial number and the manufacturer's address is found on the number plate of the machine. See illustration below.

The serial number and year of manufacture for this machine is given below. This number is important with regard to service and the correct supply of spare parts.

The machine is marked CE. This marking with appurtenant EU statement of agreement means that the machine complies with substantial health and security demands, and that it is accordance with the directives 89/392/ECC as amended by directive 91/368/ECC, 93/44/EEC and 89/336/EEC.



Year of manufacture :	

Introduction

We congratulate you on the purchase of your new Kverneland product. You have chosen a product which will give you satisfaction through a network of efficient dealers where function, finish, after sales service and spare parts are always at hand.

All Kverneland products are designed and tested in close co-operation with farmers and contractors to ensure optimal function and reliability.

Please read this manual before using your new machine. Note that the user manual refers to optional equipment, which is not mounted on your machine. The control panels are prepared for optional features, even if the machine not is equipped with the current function.

We wish you all the best with your Kverneland product.

Yours faithfully **Kverneland Underhaug AS**



Kverneland Underhaug AS Torlandsvegen 3 N-4350 Nærbø

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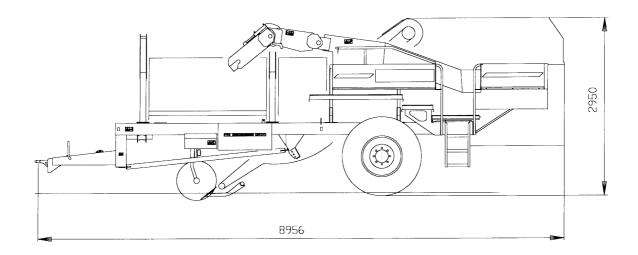
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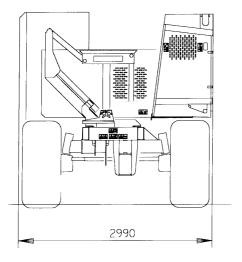
Model description

Kverneland UN 5300 is a single-row potato harvester with bunker. The machine is designed for harvesting potatoes. The first and second sieving web are mechanical driven. Remaining webs, haulm diviner web, cross conveyor and picking table, is hydraulically driven. The main sieving web has adjustable agitators. The cross conveyor consists of sieving web and hedgehog web. The working angle is infinite adjustable. Rotating deflectors are included in the separation system. Type of webs and deflector system is according to model version. The picking table offers space for 4 operators and has integrated trash web and trash chutes. The machine is delivered with a 3 or 4 ton main bunker. The main bunker has parallel lifting which provides large unloading height. The machine is available with alternative track widths, offers hydraulic lane adjustment and electric control systems. Observe! The standard of the machine may differ according to each market's specifications

Dimensions

Covers machine with horizontal main frame and standard wheel dimension 16.00/70-20"





Technical specifications basic machine

Covers machine with horizontal main frame and standard wheel dimension 16.00/70-20"

5323 5324 5333 5334 Model: Dimensions and weight Length from center drawbar yoke 8,80m Transport width (without bunker chute) 2,99m Transport width (with grader bunker) 2,99m Working width (without bunker chute) 3.93m 2.95m Transport height (without bunker chute) 5100kg 4900kg 5100kg 4900kg Gross weight 800kg 900kg Drawbar weight 800kg 900kg 4100kg 4200kg 4100kg 4200kg Axle weight

Connection to tractor

Mechanical Hitch or tractor drawbar

Hydraulical One hydraulic outlet with free return to tank or

double acting outlet with 25-50 l/min at 175 bar

Electrical 12V

Control sytem

Standard Electric

Optional Electronical prepeared for auto functions

Shares

Standard 3 blades
Optional 2 blades
1 blade

Roller discs

Diameter 690mm Distance 520-600mm

Haulm pull in wheel

Diameter 385mm

1st. sieving web

Width 750mm
Web gap (standard) 30mm
Web gap (optional) 26, 35, 40mm
Rod diameter 10mm
Sieving area 3.10m²

Flight conveyor

Speed adjustment Fixed speed,

approx. 95% of main web speed

Speed adjustment (optional)

Infinite during harvesting

Main web agitation

Type One or two rotating agitators, mechanical driven

Adjustment (standard) Mechanical
Adjustment (optional) Infinite hydraulical

2nd. sieving web

Width 0.75m Web gap (standard) 26mm

Web gap (optional) 19 coated, 24 coated, 31, 35mm

Rod diameter 9mm Sieving area 0,95m²

Distribution to cross conveyor Rubbercoated roller

Operator's manual Kverneland UN 5300

3rd. sieving web

Width 0.75m Web gap (standard) 26mm

Web gap (optional) 19 coated, 24 coated, 31, 35mm

Rod diameter 9mm Sieving area 0.75m²

Haulm deviner web

Width 0,85m Working length 2.15m

No. of strippers (standard) 2 + 3 rows of 6 strippers each No. of strippers (optional) 3 + 4 rows of 6 strippers each

Speed adjustment (standard) Fixed speed, approx. 100% of main web speed

Speed adjustment (optional)

Infinite hydraulical

Haulm pulling roller

Width 750mm

Adjustment 3 pos. horizontally, infinite vertically

No. of haulm guides 5 pieces

Primary cleaning unit

Working width 750mm

Angle adjustment Infinite mechanical Angle adjustment (optional) Infinite hydraulical

Angle adjustment (optional)

Infinite hydraulical with automatic angleadjustment

Primary cleaning unit type all-round (5323 and 5324)

Hedgehog web Short hedgehog web, all-round type
Deflector 1 2 oscillating deflectors with adjustable

working height

Deflector 2 Rotating deflector roller for remainings

Primary cleaning unit for stone separation (5333 and 5334)

Hedgehog web Long soft hedgehog web for stone separation

Deflector 1 Rotating nylon brush deflecting web with adjustable

working height

Infinite speed adjustment (optional)

Deflector 2 Rotating deflector roller for remainings

Picking table

Width main picking web 700mm
Width trash conveyor 300mm
Web gap 20mm

Speed adjustment Infinite on the run

Main bunker

Capacity 3000kg 4000kg 3000kg 4000kg Discharge height approx. 1.57-3.93m (centre drive shaft)

Wheel axle

Standard Fixed type

Optional Hydraulic wheel steering

Height adjustment 50mm

Track width (standard) 75-80cm row width
Track width (optional) 85 or 90cm row width

Wheel dimensions

Standard 16.00/70-20" Option 400/60-26,5" 500/60-22.5" 500/60-26,5"

600/55-26,5"

Technical specifications sundry optional equipment

Secondary cleaning

Clod removal unit cleaning

Grader

Grading rate Adjustment

Grader bunker

Capacity
Discharge height

Stone bunker

Hydraulically operated discharge hatch

Control system and automatic functions

Additional control panel for drawbar adjustement, wheel adjustement, discharge height and moving floor Automatic depth control
Automatic lane adjustment
Automatic angle adjustment primary cleaning unit
Automatic height adjustment picking table
Automatic filling optimization

Canopy

Canopy picking table Canopy main bunker 3000kg Canopy main bunker 4000kg

Discharge chute main bunker

Discharge chute 3000kg Discharge chute 4000kg Cleaning rollers mounted between primary

unit and picking table

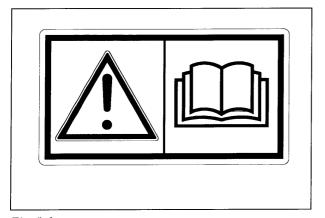
20-50mm

Profiled rollers with infinite adjustment

800 kg

1,42m or. 1,58m (centre drive shaft)

(Requires electronic control system) (Requires electronic control system)





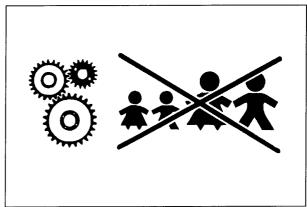


Fig. 8-2

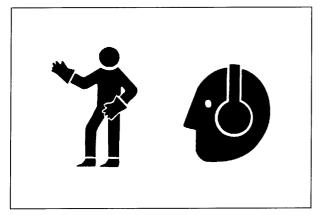


Fig. 8-3

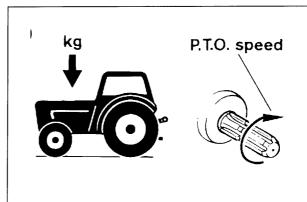


Fig. 8-4

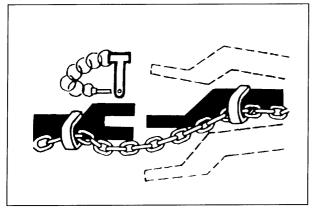


Fig. 8-5

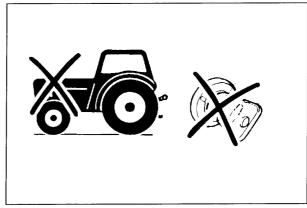


Fig. 8-6

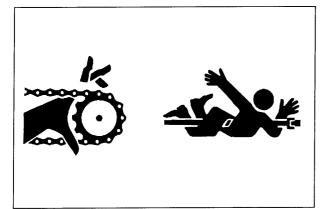


Fig. 8-7



Fig. 8-8

Safety

Before operating, adjusting or servicing the machine it is important that the safety instructions in this manual are carefully read and understood by those directly concerned (Fig. 8-1).

Whilst all care and attention has been taken in the design and production of this machine, as with all machinery there remains a certain amount of risk to personnel whilst the machine is in use. It is strongly recommended that users and operators take all possible precautions to ensure both their own safety

and that of the others that may be in the vicinity. Read and observe the safety instructions in this manual. Safety is your responsibility!

Pay particular attention to this symbol. It means that there could be a serious hazard. It emphasises precautions which have to be complied with in order to prevent accidents.

This symbol can be found throughout this manual and on the warning signs of the machine. They are for your safety and should be observed at all time.

General safety precautions

Be careful when other people or animals are close by!

Never start the machine when people or animals are close by tractor or machine. Never stand between the tractor wheels and the machine (Fig. 8-2).

Bear in mind regulations regarding the lower age limit of operators of this kind of machines.

Use of the machine

The machine should be used only for the purpose it has been designed for.

Use personal protection devices

Do not wear loose clothing which might catch in any of the moving parts. In dusty conditions an approved mask must be used (Fig. 8-3).

Take care of excessive noise level. Some tractor/implement combinations, depending on conditions, may cause noise level beyond 85dB at the operator's ears, even in a 'Q' cab. In these conditions ear defenders must be worn. Keep cab windows and doors closed to reduce noise level.

The machine must be connected to a correctly sized tractor

The weight of the tractor must correspond to the maximum weight of the machine when operated. Follow domestic law and regulations (Fig. 8-4).

Make sure that the tractor has the correct P.T.O. gear engaged. A machine designed for an input speed of 540 rpm. should never be connected to a tractor with 1000 rpm. output speed engaged. The normal P.T.O. speed is given on a label close to the P.T.O. input shaft.

Connecting machine to tractor

must always be carried out as described in this manual. If connection should be carried out with the drawbar, one of the parts (tractor's or machine's drawbar) must have a clevis. The drawbar pin must be secured with a locking pin (Fig. 8-5).

Observe national regulations regarding road transport. Some countries require the use of safety chain when a trailed machine is towed along public roads.

Think of safety while operating the machine Stop the tractor engine and remove the ignition key prior to carrying out repairs, cleaning, lubrication or maintenance on the machine (Fig. 8-6).

Safety guards

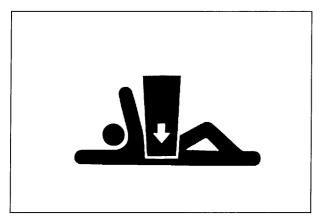
Make sure all guards are in good order and fitted correctly. Do not attempt to start the machine before ensuring this (Fig. 8-7).

Pay particular attention to the plastic guards of the P.T.O. shaft. If damaged they must be replaced. The chain locks of the guards must always be fitted on a suitable place on the tractor and the machine to prevent the outer plastic guards turning.

Hydraulics

Be very careful when operating the hydraulics. Use eye protection and gloves. Escaping hydraulic oil under pressure might penetrate into the skin and cause serious infection. See a doctor if you have been exposed to injury (Fig. 8-8).

Take care that nobody is close to the machine when the hydraulic functions are being operated.



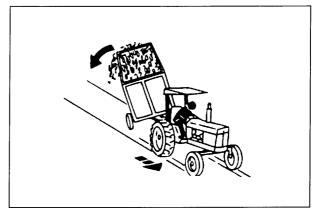
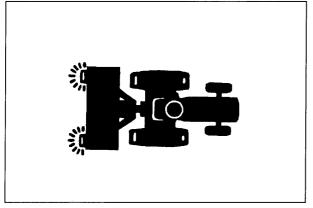


Fig. 10-1 Fig. 10-2



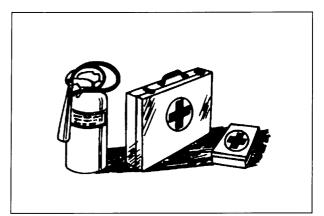


Fig. 10-3 Fig. 10-4

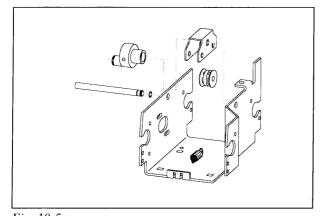




Fig. 10-5

When uncoupling machine and when leaving tractor/machine

When uncoupling, all hydraulic functions must be in neutral position. The machine must be lowered to the ground and be safely secured. If the machine has parking chocks they should be used at the wheels. Never allow children to play or stay near agricultural machinery (Fig. 10-1).

Drive safely

Be aware of your responsibility, - carelessness or negligence may cause serious injury or even death (Fig. 10-2).

Prior to transporting the machine along public roads, check wheel bolts and couplings. Disconnect or lock the hydraulic system.

Drive carefully. Reduce speed when turning and driving on uneven ground. Take care that trailed machines do not start swinging or become unstable.

Please be aware of the danger of overturning when working on slopes and in soft ground. Reduce load.

Lights

The owner and operator is responsible of providing correct lamps and reflectors on the machine when transported on public roads. Comply with public regulations (Fig. 10-3).

Safety equipment

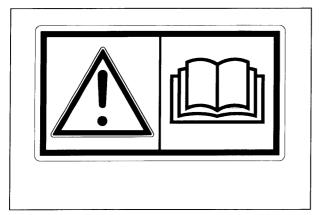
Always carry first aid equipment on the tractor. Also observe the regulations concerning fire extinguisher. When working with burning materials like hay and straw a fire extinguisher must be available at all times (Fig. 10-4).

Spare parts

For safety reasons use only original spare parts. The use of spurious spare parts will cause the Kverneland product guarantee to be invalid (Fig. 10-5).

Maintenance

Take care that the machine is properly maintained and kept in good safe working condition. Never change the basic technical construction of the machine (Fig. 10-6).



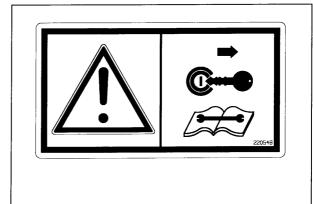
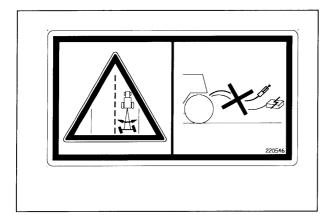


Fig. 12-1 Fig. 12-2



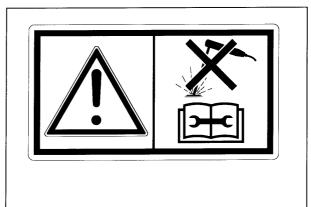
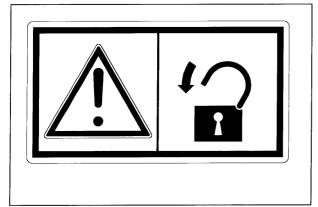


Fig. 12-3 Fig. 12-4



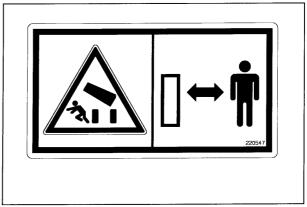
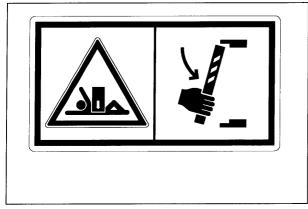


Fig. 12-5 Fig. 12-6



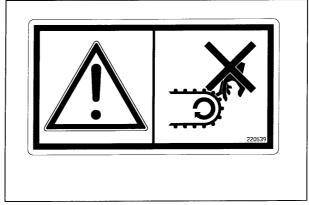


Fig. 12-7 Fig. 12-8

Supplementary safety instructions for the UN 5300

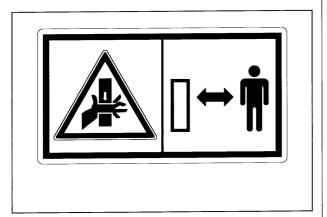


Fig. 13-1



Fig. 13-2

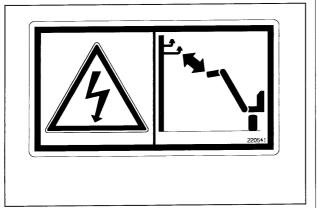


Fig. 13-3

The machine is equipped with warning signs. If any of the stickers are damaged, they must be replaced. Ordering numbers are shown on the illustrations in this paragraph.

Fig. 14-1 shows where the signs are placed on the machine.

Warning sign 220532 (Fig. 12-1). Be careful! Read and understand the instructions in this manual before the machine is put into service and before attempting adjustment/maintenance.

Warning sign 220548 (Fig. 12-2). Stop the tractor and remove the ignition key before any maintenance and service.

Warning sign 220546 (Fig. 12-3). Disconnect the control panel and hydraulics during transport to avoid activating hydraulic functions.

Warnings sign 220534 (Fig. 12-4). Disconnect all electronics before welding commences.

Warning sign 220531 (Fig. 12-5). Use transport locks during transport. Do not activate hydraulic cylinders while the lock is fitted. This might damage the machine

Warning sign 220531 (Fig 12-6). Keep distance when the bunker is lifted.

Warning sign 220535 (Fig. 12-7). Danger of trapping. Use safety leg when working under lifted bunker.

Warning sign 220539 (Fig. 12-8). Danger of trapping. Keep away from cleaning webs .

Warning sign 220536 (Fig. 13-1). Danger of trapping. Keep away from moving parts.

Warning sign 220536 (Fig. 13-2). Be careful when machine is lowered! Keep feet away from shares and wheels.

Warning sign 220541 (Fig. 13-3). Be careful when passing close to overhead powerlines. The height of the machine may exceed 5 meters when the elevator is fully raised to vertical position.

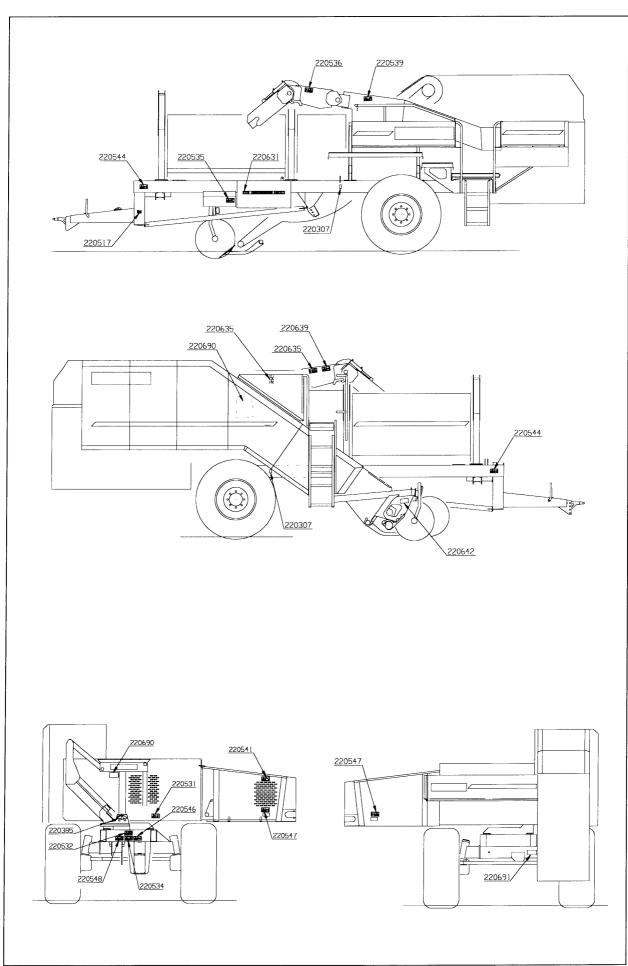


Fig. 14-1

Danger for overturning

Drive with especially care and caution in following situations to avoid danger for overturning:

- -Driving in side slopes
- -Driving with narrow track width
- -Driving with maximum load and drawbar out of centre position
- -Driving with load off centre of harvester.
- -Driving on soft soil
- -Unloading the bunker

When driving on field with loaded bunker, always use maximum track width and place the drawbar in its left position.

When lifting the bunker, the centre of gravity also rise, which makes the machine more unstable. This

requires maximum caution when unloading the bunker. The basement must be smooth and hard. The bunker must only be lifted when the machine stand still.

Hazard with use of chemicals

Always follow the manufacturer's safety precautions regarding the handling of chemicals and fertilizers.

New machine - be careful!

Read the operator's manual. Great care must be taken when starting a brand new machine for the first time. Incorrect assembly, faulty operations etc. may cause expensive repairs and loss of profit. The Kverneland product guarantee does not cover damage occurring when the instructions given in this book are not followed.



Pay particular attention to this symbol, - it emphasises operations where great care must be taken in order to avoid incorrect

assembly, faulty operations etc.

Make following checks when starting a new machine:

Check that the machine is not damaged. Assure that electric cables and hydraulic hoses have length and position that allow machine to move without causing them any damages.

Check the connections between tractor and machine.

Check that drive chains are in position on sprockets and properly tensionned.

Lubricate the machine according to lubrication charts - section 8.

Check wheel and drawbar bolts, the connections between main frame and picking table between elevator and main frame.

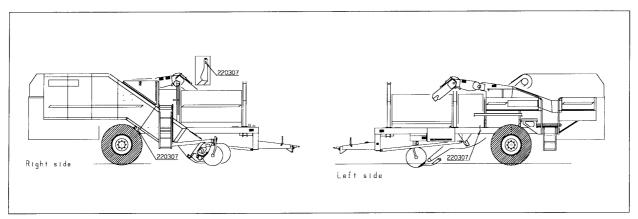


Fig. 16-1

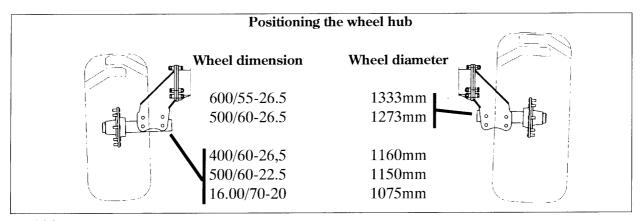


Fig.16-2

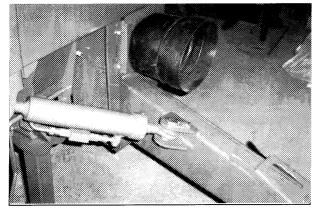


Fig. 16-3

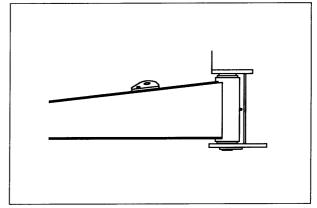


Fig. 16-4

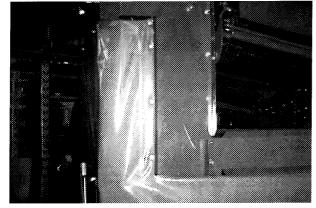


Fig. 16-5

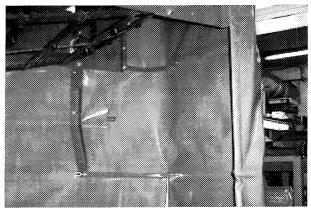


Fig. 16-6

1. Preparing a new machine

1.1 Unloading / lifting

Only use approved lifting device. The weight of the machine is given in section "Technical Specifications". Observe! Weight may vary due to optional equipment included. (Fig. 16-1)

Use the lifting beam included with the machine.

When lifting with slings: Attach approved lifting slings to the four points indicated on the machines main frame.



Make sure that slings are securely fastened before lifting. Use a guide wire to keep machine in position.

Be careful! Do not stay underneath a lifted machine.

1.2 Wheels

Fit any wheels (removed for transportation) when machine is lifted off the lorry. Make sure that the wheel axle is fitted in the correct height position (Fig. 16-2).

The wheel rims should be fitted opposite to the tractor's wheel rims.



Fasten the wheel nuts properly (conic surface on nut to face the rim). Torque 220Nm

1.3 Drawbar



Fit the drawbar and the drawbar cylinder (Fig. 16-3). Grease drawbar pin whilst still unconnected (Fig. 16-4).

1.4 Packaging and equipment

Remove all equipment and packaging stored on the machine.

1.5 Transport locks

Remove any lifting slings and other security equipment measures fitted for transportation. Mount the inside platform if removed.

1.6 PTO shaft

Mount the PTO shaft. Follow the guidelines on the shaft.

See also chapter 3.2 regarding adaption of length. There is a safety clutch fitted in the main drive line of the machine. Therefore the PTO shaft should not have safety clutch included.

1.7 Haulm guide canvas

Fit the PVC haulm guide canvas on right hand side of the machine according to separate fitting instructions (Fig. 16-5 and Fig. 16-6).

1.8 Control panels

Prepare the power cable for mounting to the tractors power supply outlet, and the cables for the control panels.

Mount the machines control panel to the control unit support above the picking table.

The system requires 12V power supply. The solenoids should work properly even if there is 10% drop in voltage.

1.9 Sensors and switches

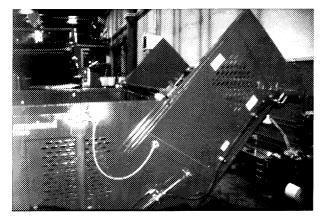
Check that all sensors are properly fastened after transport.

- 1. Sensor for wheel steering (analogue)
- 2. Sensor for auto dept. control* (microswitch)
- 3. Sensor for auto levelling cleaning web* (analogue)
- 4. Sensor for automatic height picking table* (ultrasound)
- 5. Sensor for filling optimization* (microswitch)

Analogue sensors are inductive (= «feels steel»)

Microswitches record on/off positions.

Check clearance sensor/steel prior to use. This should be between 2-6mm.





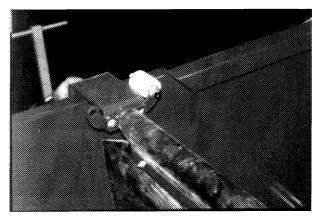


Fig. 18-2

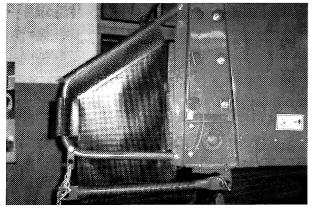


Fig. 18-3

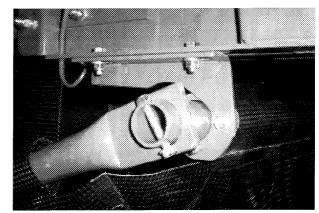


Fig. 18-4

1.10 Optional equipment

1.10.1 Moving bunker end curtain

Fit sliding frame with nylon rollers towards inner end of bunker (Fig. 18-1).

Adjust distance between roller sections achieving ball bearings roll touch bunker panel. Use the shims provided (Fig. 18-2).

1.10.2 Bunker discharge chute

Fit the side canvas onto the side frame sections. Attach them at the end of the bunker (Fig. 18-3).

Mount the brackets for the discharge chute under the bunker (Fig. 18-4).

Slide the four tubes into the slots of the canvas chute. Connect with bolts.

Note that the transport width is 10cm wider with the brackets.

See separate assembly instructions.

1.10.3 Stone hatch

The stone hatch and the cylinder are mounted to the main frame, underneath the picking table.

The hatch is operated from the tractor cab panel. See chapter 4 and 5.

1.10.4 Grader

Contact your Kverneland dealer.

1.10.5 Grading bunker

Contact your Kverneland dealer.

1.10.6 Canopy picking table

See separate assembly instructions.

1.10.7 Canopy bunker

See separate assembly instructions.

1.11 Final control

Check that no machine parts can block belts or hydraulic functions when the machine starts.

Check wheel bolts, wheel axle connectors and drawbar connectors.

Check the oil level of the tank (level glass on the tank). Correct level at horizontal machine is upper half of level glass. Hydraulic oil type HD46 is filled at the factory. Let the pump run for some minutes at PTO speed of approx. 500 rpm.

Test all mechanical and hydraulic functions.

2. Tractor requirements

2.1 Engine power

ModelMinimum engine power

UN 5323 / 5333 80 hp UN 5324 / 5334 90 hp

2.2 Hydraulics

25-50 litres/min. at 175 bar (tractor running at required engine speed).

One single acting hydraulic outlet with free return to oil tank or one double acting outlet.

The back pressure should not exceed 10 bar.

2.3 Drawbar

Hydraulic hitch or drawbar.

Use of drawbar will transfer weight from the front to the rear of the tractor. This might reduce the tractors steering property.

2.4 Electric power supply

The electric/electronic controls require a steady 12V power supply.

Use the power supply cable included with the machine to connect battery.

The solenoids can be operated at 10.5V power (measured at the solenoid), while the electronics require min. 11V input power (measured at the «black box»).

Light connections uses standard DIN socket.

2.5 P.T.O. shaft

540 rpm

13/8" 6 splines.

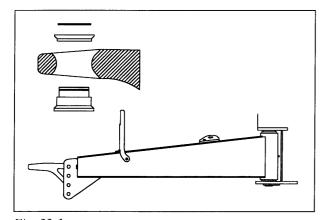


Fig. 22-1

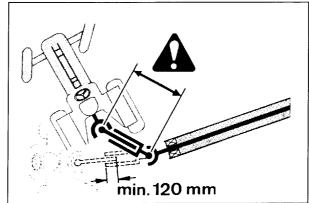


Fig. 22-2

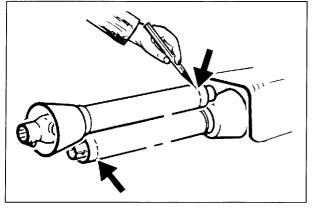


Fig. 22-3

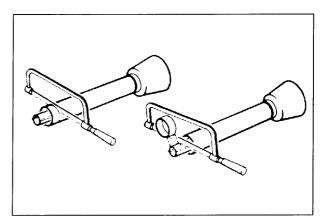


Fig. 22-4

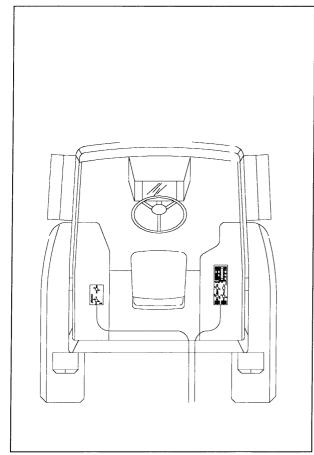


Fig. 22-5

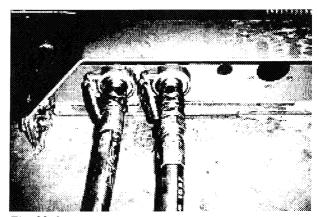


Fig. 22-6

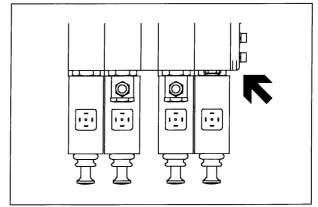


Fig. 22-7

3. Connection to tractor

3.1 Drawbar height

Adjust drawbar height for main frame to be parallel with the ground.

When attaching to drawbar use the pipe sleeve, lock ring on top (Fig. 22-1).

3.2 P.T.O. shaft



When starting a new machine the length of the P.T.O. shaft must be adjusted to allow it to slide freely yet have adequate overlap (Fig.

22-2). Both ends must be cut equal when shortening the shaft (Fig. 22-3 and 22-4).

The overlap must also be checked when connecting to another tractor. Fasten the safety chains and check that the axle can move freely in both directions.

See the shaft manufacturer's own information which is attached to all new shafts.

3.3 Electric connections

- 1. Connect the power cable to the tractors power supply. Check that the outlet voltage is 12V.
- 2. Place the control panel in a proper position on the drivers right hand side (Fig. 22-5). If the machine is fitted with an extra control panel, place this on the left hand side.
- 3. Mount the data cable to the control panel.

See chapter 4 regarding electric controls and 5 regarding electronic controls.

3.4 Hydraulics

The harvesters hydraulic hoses are identified as follows (Fig. 22-6):

Flow: Short quick release coupling

Return: Long quick release coupling

(a non return valve is fitted in

the return line).

return will damage the machine's hydraulic

Avoid return connection which gives a high back pressure (above 5-10 bar).

The flow hose can be connected to a single acting spool valve and a return hose with non-resistance oil tank connection. Missing

valves and oil motor.

When the machine is connected to a John Deere tractor (or other tractors with closed centre hydraulics), the harvester's spool valve centre must be closed. (The pin screwed into its stop, accessible from underneath the block) (Fig. 22-7). When using other types of tractors this screw must be screwed fully out with the head level with the central block edge.

When working in dusty conditions, the top of the valve bank should be covered by some kind of filter material (rubber sponge) in order to prevent dust from intruding the valves through the caps on top of the spool guides.

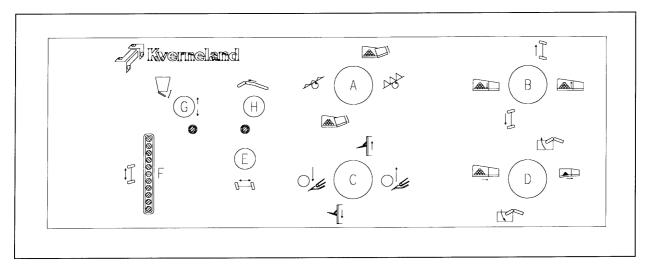


Fig. 24-1

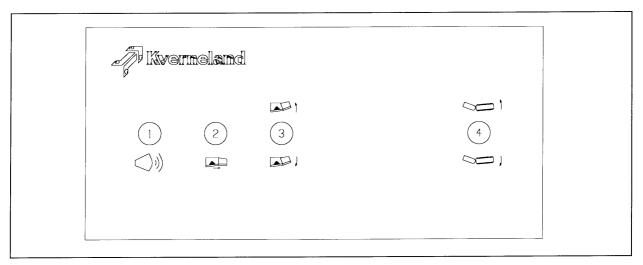


Fig. 24-2

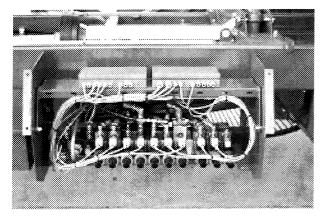


Fig. 24-3

4. Operating the electric control system

4.1. Description

The electric control system consists of:

- -Control panel tractor (Fig. 24-1)
- -Control panel picking table (Fig. 24-2)
- -Relay unit on the machine (Fig. 24-3)

The valve block is fitted with electromagnetic spool valves, which are operated from the control panels.

The electric control system may include automatic wheel centre positioning. Beyond that, no possibilty for further auto function.

4.2 Connection

Connect the electric plugs directly to the battery to ensure satisfactory power supply.

Connect the datacable from the relay / black-box to the control panels.

4.3 Control panel tractor

(Fig. 24-1). Light in the diodes indicates power supply. The panel is prepeared for operating extra functions, even if the machine is not equipped with this functions.

Toggleswitch G:

Stone hatch* open - close

Toggleswitch H:

Drive picking table on - off

Toggleswitch H:

Picking table drive on - off

Toggleswitch E:

Automatic wheel centring

Diodes F:

Indicates the wheel position. (Requires this function fitted)

Green: The machine turns left
Red: Wheels in center position
Yellow: The machine turns right

Joystick A:

- 1. Main bunker end up -down
- 2. Agitation* intensity

Joystick B:

- 1. Wheel steering right left
- 2. Main bunker up down

Joystick C:

- 1. Shares up down
- 2. Drawbar right left

Joystick D:

- 1. Picking table end end up down
- 2. Roller floor main bunker (joystick to the left)
- 3. Roller floor grader bunker* (joystick to the right)

4.4 Control panel picking table

(Fig. 24-2)

- 1. Audible alarm
- 2. Grader bunker floor drive
- 3. Grader bunker end up down
- 4. Cross conveyor tilting up down

4.5 Relay unit

The relay unit is fitted over the valve block at the left hand side of the machine. The power supply and data cables are connected to this unit.

4.6 Automatic wheel centring*

The function is activated with toggle switch E. The function is disactivated by activating the wheel steering joystick.

The wheel steering sensor is fitted on the left kingbolt. The distance between the magnet must be between 2 og 6 mm.

The sensor cable must be adjusted if the track width is changed.

Operator's manual Kverneland UN 5300

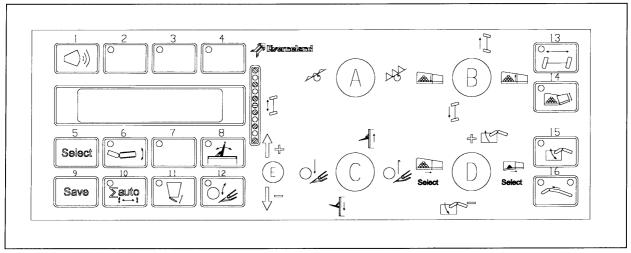


Fig. 26-1

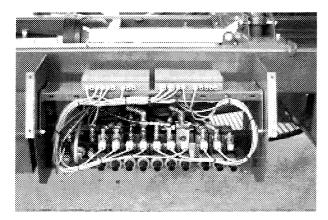


Fig. 26-2

5. Operation the electronic control system*

5.1 Function and structure

The electric control system consists of:

-Control panel tractor (Fig. 26-1)

-Control panel picking table (Fig. 28-1)

-Extra control panel for positioning and bunker operations (Fig. 28-2)

-Driver unit fitted on the machine (Fig. 26-2)

The valve block is fitted with electromagnetic spool valves, which are operated from the control panels' joysticks, toggle switches and buttons.

The computer operates continuously, reading information from inputs (sensors) and panel, comparing information and thereafter activating outputs (spool valves).

The electronic control system can be fitted with following auto functions:

Automatic wheel centring Automatic lane adjustment Automatic angle adjustment cross conveyor Automatic height adjustment picking table Automatic bunker filling

5.2 Connection

Connect the electric plugs directly to the battery to ensure satisfactory power supply.

Connect the data cable from the driver module / black-box to the control panels.

5.3 Control panel tractor

(Fig. 26-1). Appearing of text in the display shows that the power supply is connected. The panel is prepared for operating extra functions, even if the machine is not equipped with this functions

G. Display:

Shows alphanumeric information (numbers and letters). Standard display mode shows the wheel position in degrees, and in addition position of other auto-levelling functions if mounted. Standard display mode can be changed using «Select» and «Save». When activating/deactivating auto functions this is displayed.

E. Toggle-switch:

The toggle-switch is used in combination with the keys. The switch are used to change working positions and operate hydraulic functions which do not have their own joystick (bunker end/ stone hatch). Activate the current function, and then press the toggle-switch to activate the function.

Example on activating the bunker end:

- 1. Press shortly key no. 14, bunker end/stone hatch. The display indicates now «Hopper».
- 2. Activate the toggle switch within 6 seconds. The display returns to standard view after 6 seconds.

Diode lights F:

Indicates the wheel position. (Requires automatic wheel centre positioning fitted)

Red: The machine turns left Yellow: Wheels in centre position Green: The machine turns right

Joystick A:

1. Main web agitator adjustment*

Joystick B:

- 1. Wheels turn right left*
- 2. Main bunker up down

Joystick C:

- 1. Shares up down
- 2. Drawbar right left

Joystick D:

- 1. Picking table end up down
- 2. Roller floor main bunker (joystick to the left)
- 3. Roller floor grader bunker* (joystick to the right)

Keys 1-16:

- 1. Audio alarm (separate bugle on the machine)
- 2. Not in use
- 3. Not in use
- 4. Not in use
- 5. Select: Chooses standard display view (long touch) Forward in menu (short touch)
- 6. Select: Activate cross conveyor tilting (short
 - touch)*

Adjust angle by operating the toggle

switch

Automatic angle control (long touch)*

7. Not in use

8. Select: Automatic lane adjustment*

9. Save: Saves data/positions (long touch)

Backwards in menu (short touch)

10. All auto Activates more auto functions simulta

neously

11. Select: Stone box

Adjust angle by operating the toggle

switch*

12. Select: Automatic depth control*

13. Select: Automatic wheel centre positioning

14. Select: Bunker end control

Operate by toggle switch

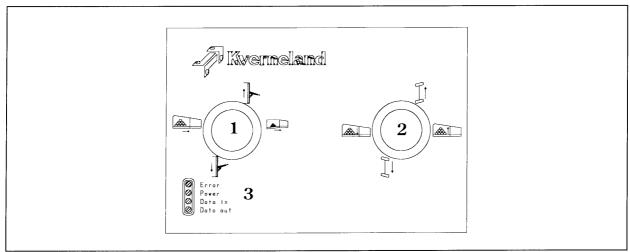


Fig. 28-1

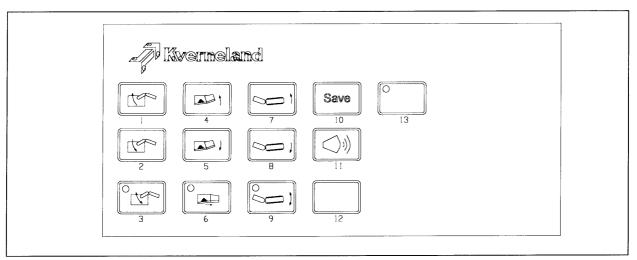


Fig. 28-2

15. Select: Automatic height adjustment picking

table end*/automatic bunker filling*

16. Operate: Picking table start - stop

5.4 Extra control panel tractor*

(Fig. 28-1) This unit have functions for positioning of wheels, drawbar, and operating the main bunker.

Joystick 1:

- 1. Drawbar right left
- 2. Roller floor main bunker (left)
- 3. Roller floor grader bunker* (right)

Joystick 2:

- 1. Wheel steering right left
- 2. Main bunker up down

Diodes:

Error: System faults. See chapter. 9.3.

Power: Indicates power supply

Data in: Receiving data Data out: Transmitting data

5.5 Control panel picking table

(Fig. 28-2)

- 1. Picking table end up
- 2. Picking table end down
- 3. Automatic height adjustment picking table end*/ automatic bunker filling*
- 4. Grader bunker end up* (single control only)
- 5. Grader bunker end down* (single control only)
- 6. Roller floor grader bunker* (long touch = start/ short touch = stop)
- 7. Cross conveyor up*
- 8. Cross conveyor down*
- 9. Automatic working angle cross conveyor*
- 10. Save: Save current work position
- 11. Audible alarm
- 12. Not in use
- 13. Not in use

5.6 Automatic mode operation

The auto functions are activated by a long touch on the relevant key, until the red diode light up. There is also a display message telling which function that is in auto mode. The auto function is deactivated with a short touch on the relevant key, or by activating the relevant joysticks.

When entering auto mode, the machine will go to the last known auto-position. This position is shown on the display. When setting a new work position, use the joystick/toggle switch to find desired position. Then press the SAVE key with a long touch, and at last press the relevant function key with a short touch.

The system can in addition to the neutral position, store one working position. The wheel steering, however, is capable to store two offset working positions in addition to the neutral (zero) position, one to the left and one to the right.

To alternate between the different working positions, first activate the relevant auto function and then use the toggle switch <+> or <->. The toggle switch must be activated within 6 seconds after the auto key is activated. The selected working position is shown in the display.

Example of saving and using the auto function:

Saving 50 offset wheel position:

- 1. Adjust the wheels to desired position (50)
- 2. Press SAVE until «STORE POSITION» is shown in the display.
- 3. Activate the auto wheel position key with a short touch.
- 4. 50 offset work position is now saved.

Alternate between neutral position and offset:

- 1. Activate auto wheel position
- 2. Activate the toggle switch within 6 seconds. Use the toggle switch <+> or <-> to the desired position is displayed, 0o or 5o.

5.7 All auto

All auto function activates or deactivates simultaneously all desired auto functions and picking table drive by on key touch (Fig. 30-1).

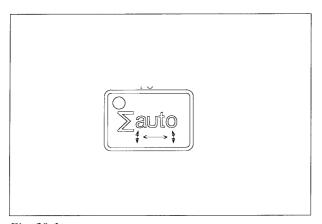
Any separate auto function is stored under All auto following this procedure:

- 1. Activate desired functions to be operated together (example: auto wheel centre positioning, auto lane adjustment and picking table drive start)
- 2. Press <Save> till <Store position> is displayed
- 3. Press < All Auto> till diode lights

The chosen functions are deactivated simultaneously by pressing <All auto>. A single functions may be deactivated by overriding till current function's joystick or key. If one or more functions are deactivated, the diode of the <All auto> key is turned off.

Changing the All auto function should be done by storing the desired functions once more, as described above.

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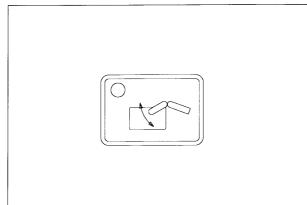


Fig. 30-1

Fig. 30-2

5.8 Automatic bunker filling

The function is activated by key 15 on the control panel (Fig. 30-2). The function is deactivated by pressing the same key, or by activating relevant joysticks.

When the function is active, the end of the picking table is automatically lowered into the bunker. A sensor placed on the picking table end monitors the distance to the potatoes.

When the potatoes activates the sensor, the picking table lifts automatically. This procedure is looping until the picking table has reached its top position. When the potatoes activates the sensor at the picking table's top position, the bunker floor moves automatically until the sensor is deactivated. When the moveable bunker end curtain has reached the outer position of the bunker, a stop sensor is activated. This sensor stops the bunker floor and alerts the driver.

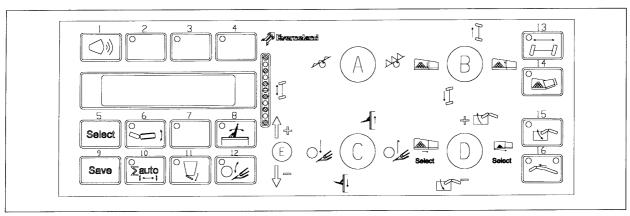


Fig. 32-1

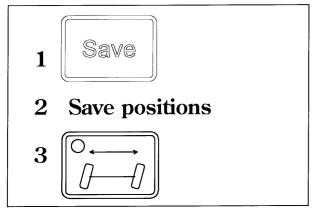


Fig. 32-3

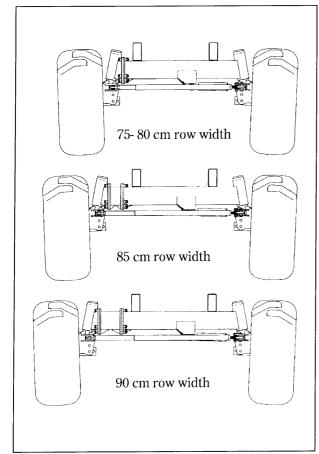


Fig. 32-5

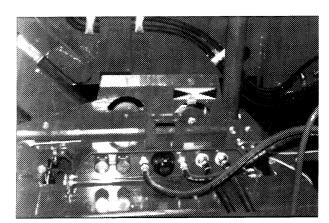


Fig. 32-4

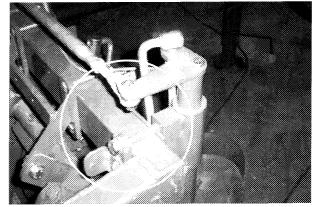


Fig. 32-6

6. Positioning and row width adjustments

6.1 Lane adjustment

The lane adjustment is hydraulically operated with a joystick at the control panel (Fig. 32-1). The diabolo rollers must run in the middle of the ridges.



The lane adjustment must only be activated when the harvester is going forwards, or the lifting unit is lifted from the ground

6.1.1 Automatic lane adjustment*

Electronic control system can be fitted with automatic lane adjustment. This option make the diabolo running in the middle of the ridges, even if the distance between the tractor and the ridge varies. A sensor records the position of the diabolo, and if there is variance, the system correct the position by activating the lane adjustment cylinder.

The auto mode is activated by a touch on the auto mode key 8 when lifting unit has been lowered. The auto mode is deactivated by a touch on the relevant key, or by using the lane adjustment joystick.

6.1.2 Stability

The position of the drawbar affects the stability of the machine. The stability is at its best when the drawbar is turned left.

During harvesting, and especially when turning, and unloading the bunker, the drawbar must be positioned to the left.

6.2 Wheel steering*

The wheel steering is controlled with joystick B on the panel (Fig. 32-1). The wheels' position is displayed by the indicator in front of the harvester (Fig. 43-4) or in the display of the control panel (only when automatic wheel centre positioning is fitted).

6.2.1 Automatic wheel centre positioning*

This function is activated by key 13 on the control panel (Fig. 32-1) The auto mode is deactivated by a touch on the relevant key, or by using the relevant joystick.

The position is indicated by the light diodes on the panel (Fig. 32-1).

6.2.2 Alternative work positions

The electronic control system can save two alternative work positions, one to the right and one to the left.

The offset work function can e.g. be used in hilly areas, or to store the wheel position which are used if the machine must run offset during opening of the field. Saving and using the auto function is done as follows:

Saving of 50 offset wheel position (Fig. 32-2):

- 1. Adjust the wheels to desired position (50)
- 2. Press <SAVE> until <STORE POSITION>» is shown in the display.
- 3. Activate the auto wheel position key with a short touch.
- 4. 50 offset work position is now saved.

Alternating between neutral position and offset position (Fig. 32-3):

- 1. Activate auto wheel position
- 2. Activate the toggle switch within 6 seconds. Use the toggle switch <+> and <-> to the desired position is displayed, 0O or 5O. The wheels will automatically move to displayed position.

6.3 Track width

The standard machine has a wheel axle suitable for row widths of 75-80cm. Extensions suitable for 85 or 90cm row widths are available (Fig. 32-5).

When splitting a field at 75cm row width and below, the machine has to run a little aslant in order to position lefthand wheel inbetween the rows. This assuming wheel steering is fitted.

The machine shall have maximum track width when operated in hilly areas and soft soil and it is equipped with 4t main bunker and grader bunker.

6.4 Roller discs

The distance between the roller discs can be adjusted infinitely by moving its bracket on the beam (Fig. 32-6). See also chapter 7.3.

		Main web speed (km/h) at given PTO speed				
	Exchange	300 rpm	350 rpm	400 rpm	450 rpm	500 rpm
Standard machine Alt. speed*	3,1:1	3,0	3,4	3,9	4,4	4,9
Sprocket 25t	3,1:1	3,0	3,4	3,9	4,4	4,9
Sprocket 21t	3,7:1	2,5	2,9	3,3	3,7	4,1
Sprocket 19t	4,1:1	2,2	2,6	3,0	3,4	3,7

Fig. 34-1

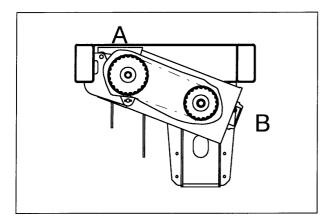


Fig. 34-2

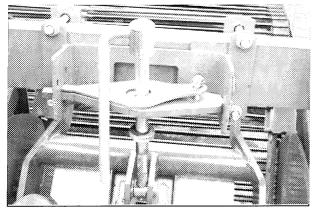


Fig. 34-4

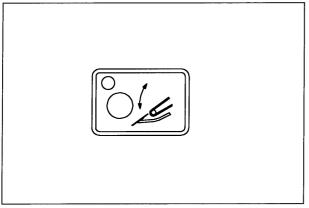


Fig. 34-6

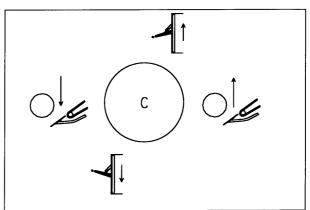


Fig. 34-3

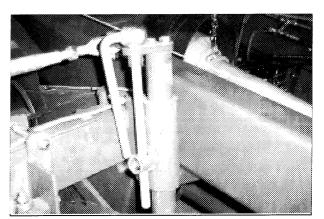


Fig. 34-5

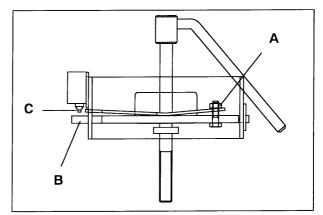


Fig. 34-7

7. Settings and operating

Wrong settings and use of the machine, and also uncritical use of the cleaning facilities increases the risk for damaging the crop. Therefore use the cleaning facilities with care, and never more than

the conditions requires. Changed soil and haulm conditions requires alternative settings of the machine to ensure a damage-free harvest with maximum capacity.

Mature crop and satisfactory soil temperature is a requirement for a damage-free harvest.

7.1 P.T.O. speed revolutions

The recommended P.T.O. speed is 300-500 rpm. Optionally the machine can be fitted with alternative speeds which reduces the revolutions with 16 and 25%. The speed reduction is done by changing sprocket B in the front (Fig. 34-2).

Speed reduction offers:

-Increased rpm on tractor if the tractor has to low engine power or to small hydraulic capacity. -Better possibility for optimum relations between rpm and forward speed.

Revolutions must be adjusted to forward speed. When the main digging web has the same speed as the tractor, the most gentle handling of the potatoes is achieved. See chart (Fig. 34-1).

7.2 Opening of the field

Adjust the drawbar to the left to achieve sufficient distance between the ridge and the tractor.

When opening the field use the wheel steering to get the machine's left hand wheel to run in the furrow. To ease the positioning, lift the bunker a bit at the beginning. If the machine is equipped with electronic control system, is it possible to save the wheel position to for later use. (See chapter 5).

7.3 Depth control

7.3.1 Mechanic depth control

The lifting unit is raised and lowered hydraulically by means of the control panel joystick.

Share depth is adjusted using the diabolo (Fig. 34-4). One turn of the adjustment screw corresponds to approx. 6mm share depth change.

When the soil contains a lot of clod and stones accurate depth adjustments is extremely important.

The large side discs will cut the haulm etc., and should normally be adjusted to penetrate approx. 5 cm (2") into the soil. Adjustment is carried out by means of the screw on each disc stem (Fig. 34-5). Note! Excessive cutting depth can cause the share to be lifted (particularly in heavy and stony soil) resulting in potential damage.

7.3.2 Automatic depth control*

The automatic, hydraulic depth control reduces pressure on the diobolos. The function is activated with a key on the control panel (Fig. 34-6).

A micro switch C fitted in front of the machine monitor the lifting unit (share) position. Signals from the switch are fed into the computer (Fig. 34-7)

The pressure on the diabolos is altered by changing the pre-tensionning on the plate spring D which activates the switch C. To increase pressure tighten the screw A.

The computer is programmed so that the switch try to maintain mid-position (neutral). A reaction delay in the system avoids a too «busy» depth control, that is; to avoid depth compensation for every small disturbance (small dumps, when hitting rocks etc.).

7.3.3 Retrofitting and control of automatic depth control

When fitting automatic depth control, avoid damaging the micro switch.

- 1. Loosen the screw A.
- 2. Raise the plate B at it's maximum
- 3. Press the micro switch down so the pin is pres sed all the way in.
- 4. Fasten the micro switch.
- 5. Adjust the screw A to find desired diabolo pressure.

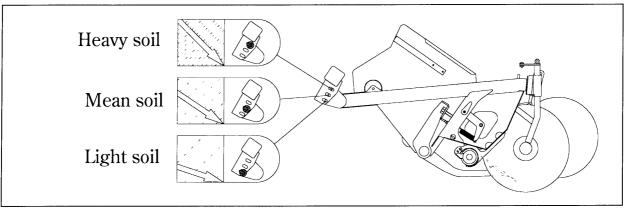


Fig. 36-1

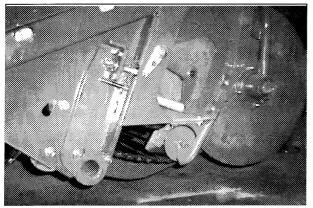
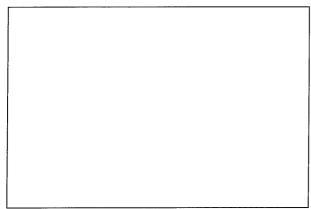




Fig. 36-2 Fig. 36-3



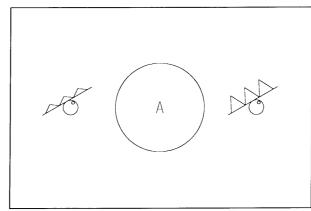


Fig. 36-4 Fig. 36-5



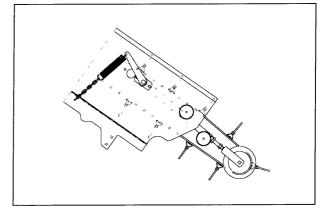


Fig. 36-6 Fig. 36-7

7.4 Adjusting the haulm pull-in rollers

The haulm pull-in rollers rotate on the belt. If they do not grip the haulm, spring tension must be increased (Fig. 36-2). Check that the rollers do not touch the side plate or side disks. Note that the rollers must be angled, with minimum clearance towards the side plate of lower edge.

If gap between disc and pull-in roller is too wide, 25mm wide roller extensions are available (option).

7.5 Soil seeking

The soil seeking can be adjusted by changing the lifting units connecting point to the main frame (Fig. 36-1).

A. Large soil seekingB. Normal soil seekingC. Small soil seekingLight conditions

Note that all three holes must be overlapped when changing connecting point.

7.6 Share angle

The share angle can be adjusted using the screw B on the share holder (Fig. 36-2). This also adjust share height in relation to the main digging belt.

A. Plane share Small soil seeking
B. The share is tangent to the main web This is the most gentle position of the shares.
C. Step share Large soil seeking

When there is a problem with haulm attaching itself to the share frame sides, this can either be avoided or reduced by increasing the lifting units ground clearance:

- 1. Lower the share. Steeper share angle
- 2. Adjust the diabolo for compensating the digging depth.
- 3. Move the digging units hinge point down in Settings and operatingorder to keep soil seeking.

7.7 Soil separation

7.7.1 Web agitation

The intensity of the agitation changes by Lifting or lowering the agitator(s) (Fig. 36-3).

Mechanical adjustment:

To be adjusted by repositioning the stay on the right-hand side of the main web (Fig. 36-4).

Hydraulic adjustment:

Operate the joystick on the control panel (Fig. 36-5). The intensity can be observed by the indicator placed in the front of the frame.

Due to danger of damaged potatoes, use as little agitation as possible.

7.7.2 Flight conveyor

The fixed speed of the flight conveyor is approx. equal to the main web speed, thus handling the potatoes most gently.

The optional infinite speed adjustment offers maximum control and capacity. Speed is controlled by the knob B on the picking table (Fig. 36-6).

Reduced speed increases sieving and clod crushing capacity.

The flight conveyer should run at least at the same speed as the forward speed of the harvester in order to prevent soil from bulldozing at the shares. If the conveyer speed is reduced to this level and there is still need of more sieving capacity, the tractor engine speed should be increased to run the main web faster.

In order to avoid crop damages the end roller unit must have a low pressure on the crop. The pressure can be adjusted by slacken or tension the spring (Fig. 36-7).

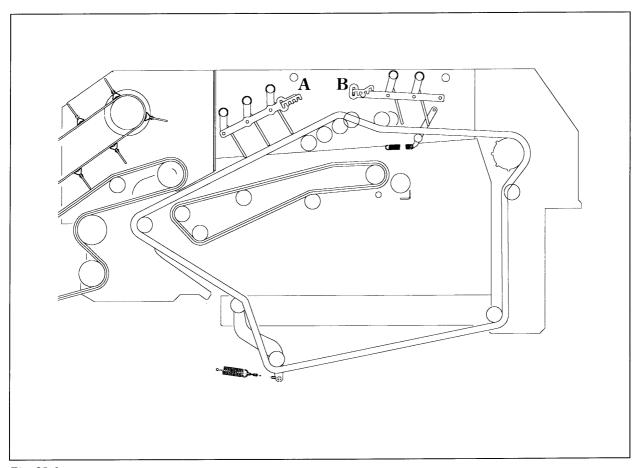
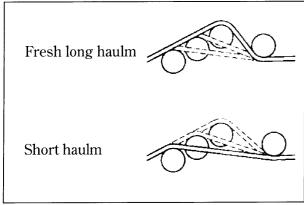


Fig. 38-1





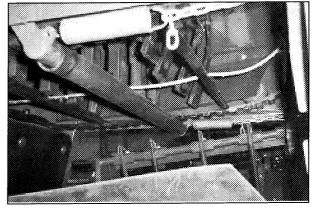


Fig. 38-3

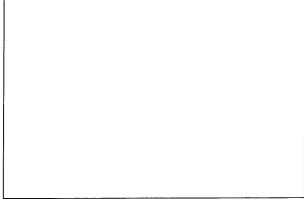


Fig. 38-4

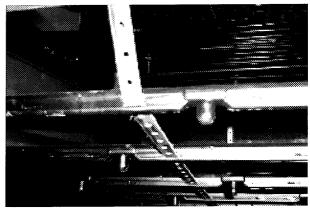


Fig. 38-5

7.8 Haulm separation

7.8.1 Flight conveyor

The flight conveyor may cause tubers to get loose from the roots if operated at a speed lower than the main web. However, if speed is reduced too much, uneven flow of haulm may cause haulm removal to get worse.

7.8.2 Haulm (diviner) web

The haulm web speed is approx. equal to the main web speed.

The optional infinite speed control offers maximum control and capacity. Speed is controlled by the knob A on the picking table (Fig. 36-6).

Large quantities of haulm
Long haulm
High speed
High speed
High speed
High speed
Low speed
Low speed

Web path

The position of the top rollers can be changed due to different conditions (Fig. 38-1 & Fig. 38-2).

Long haulm/Green haulm Aggressive path (sharp S-curve)

Short haulm/Dead haulm Non-aggressive path (gentle S-curve)

Haulm strippers

The machine is equipped with 5 adjustable rows with adjustable and spring loaded haulm strippers (Fig. 38-1). Two more rows can be fitted (option).

The efficiency is increased by reducing the distance to the web. The distance is adjusted with levers at the left hand side of the haulm web.

Stripping bar

The stripping rod underneath the haulm diviner web pulls off potatoes still attached to the haulm. The roller is spring loaded and can move away if overloaded. In working position bar should be close to the web (Fig. 38-3).

Haulm web screening

Straps in the web decrease the gap of the web increasing transport of short haulm. Totally 3 straps can be fitted (Fig. 38-4). The straps are assembled through slots in the web (Fig. 38-5).

7.8.3 Haulm roller

The haulm roller is fitted between the 3rd. sieving web and the hedgehog web (Fig. 40-1).

The horizontal position can be changed by adjusting the arm C. Loosen bolt on top, raise the lock plate and move the arm. Vertical position can be changed by adjusting bolt B. Spring tension is adjusted with bolt A.

When the roller is moved under the web its efficiency is decreased. Opposite direction increases the efficiency. In normal conditions the haulm roller should be used in the centre position. In the outer position the roller is able to catch the potatoes and damage them. Due to this problem this position is only for difficult conditions.

Observe! A high web rod profile (rubber coated rods) may increase risk of crop damage at the haulm roller.

The roller is most efficient when the haulm is distributed over the whole web width. This is controlled by adjusting the angle of the cross conveyer.

Normal distance between the haulm roller and the cross-conveyer is approx. 2-3 mm.

7.8.4 Haulm guides

The spring loaded haulm guides adjusts the quantity of haulm which is let into the haulm roller (Fig. 40-2). The gap between the guides and the web can be adjusted by bending the top plate of the guides.

Minimum clearance to the web is 10 mm. Spring load is adjusted with chain A.

In order to reduce damages, always use as few haulm roller guides and as little spring load as possible. If there is no need of haulm

separation at the roller, move roller inwards and remove all haulm guides.

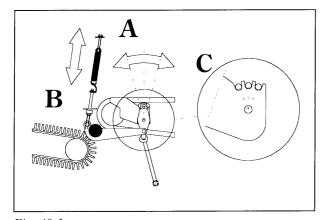


Fig. 40-1

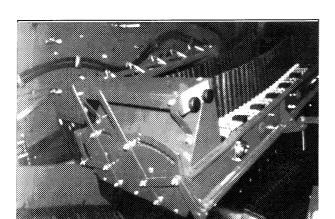


Fig. 40-3

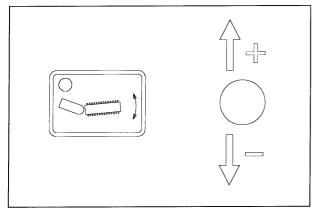


Fig. 40-5

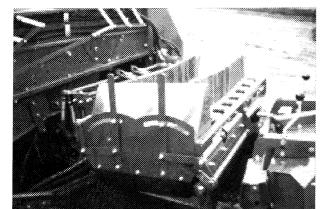


Fig. 40-7

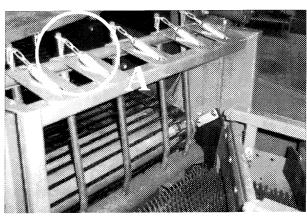


Fig. 40-2

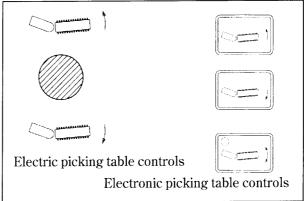


Fig. 40-4

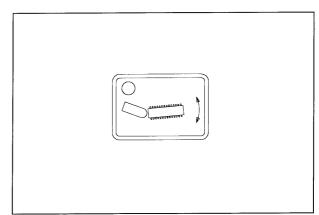


Fig. 40-6

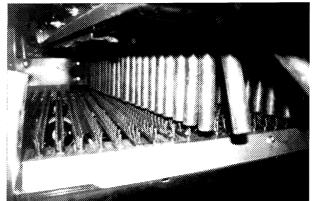


Fig. 40-8

7.9 Clod and stone separation

Separation unit includes the hedgehog web, the moving deflector and the powered deflector roller. The hedgehog web type and deflector type depends on models.

The separation depends on:

- -type of soil and content of stones
- -working speed
- -characteristics of tubers

7.9.1 Hedgehog web

Adjust the angle of the hedgehog web and the height of the moving deflector in order to separate stones and clods effectively from the potatoes. Correct position is when some potatoes are passing to the trash conveyor.

Steep angle - low degree of separation, easy crop flow

Level angle - high degree of separation

Hedgehog speed control

Adjust speed by turning knob A on the separation unit (Fig. 40-3).

Mechanical angle adjustment:

The angle is adjusted by turnbuckle behind cross conveyer.

Hydraulic angle adjustment*:

Operated from picking table panel (Fig. 40-4). If electronic control system is fitted, this function can even be operated from tractor cab (Fig. 40-5).

Automatic angle adjustment:*

Activate function by pressing the key on the tractor panel (Fig. 40-6). The chosen angle is kept constant independent of ground slope. See chapter 5 regarding setting of proper working angle.

7.9.2 Moving (rotating) rubber finger deflectors

The rotating rubber finger deflectors and the short finger type hedgehog web offers the best separation of clods etc. when content of stones is low. (Fig. 40-7).

Height adjustment

Operate the two levers in front of the deflector unit. If necessary a repositioning of the attachments to the cross conveyor frame is possible (Fig. 40-7 A, B, C, D, E). Deflector unit should be parallel to the hedgehog web.

The forward deflector should distribute crop onto the picking table in a way that makes it easy for pickers to control crop. The basic setting is 25mm gap to hedgehogs. (Fig. 40-8).

The rear deflector should be set according to need. In bad conditions the quantity of potatoes in the trash conveyor should allow one operator to be fully occupied with picking potatoes off trash conveyor. Basic setting is 5mm gap to hedgehogs. (Fig. 40-8).

Speed control

The speed of deflectors is adjusted by operating knob B on the separation unit (Fig. 40-3).

Low speed Large separation capacity
High speed Large transport capacity,
decreased separation capacity

7.9.3 Moving nylon brush web

This deflector type is combined with long finger hedgehog web providing the best stone separation. (Fig. 42-1)

Height adjustment

See chapter 7.9.1.

Speed adjustment

See chapter 7.9.1.

7.9.4 Powered deflector roller

The deflector roller at the end of the hedgehog web controls the flow of clods, stones and potatoes being transferred to the trash web, or passing directly to the ground. Working height is adjusted by the two cranks B (Fig. 42-2).

The roller position should transfer stones and potatoes on to the trash web, while soil and clods are passing underneath.

7.9.5 Cleaning rollers*

The cleaning rollers are positioned between the hedgehog web and the picking table (Fig. 42-3). No adjustments necessary.

7.9.6 Stone box*

The stone box hatch is hydraulically operated from the tractors control panel.

Electric controls

Use toggle switch G (Fig. 24-1)

Electronic controls

- 1. Activate key 11, stone box (Fig. 26-1)
- 2. The hydraulic function is controlled by operating toggle switch B (Fig. 26-1).

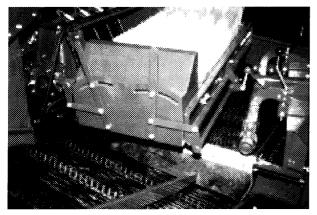


Fig. 42-1

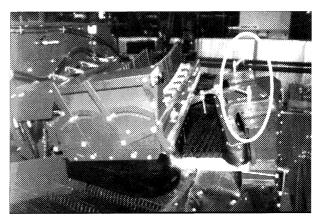


Fig. 42-2

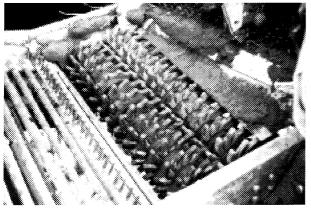


Fig. 42-3

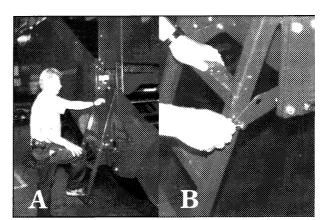


Fig. 42-4

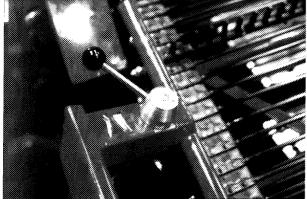


Fig. 42-5

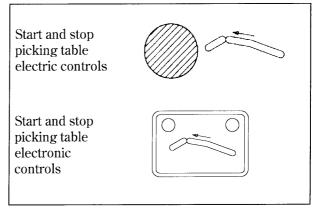


Fig. 42-6

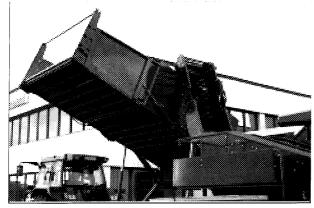


Fig. 42-7

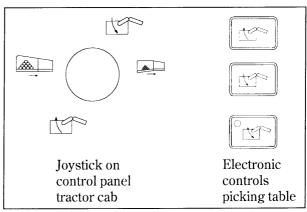


Fig. 42-8

7.10 Picking table

7.10.1 Access

Release transport in order to put right-hand ladder in working position (Fig. 42-3 A).

Release and reposition lock plates in order to put lefthand ladder in working position (Fig. 42-3 B).

The gate on lefthand side should be closed when machine is operating.

7.10.2 Speed control

The picking table is powered by the tractor hydraulics. The speed is adjusted by the lever A at the picking table's lefthand side (Fig. 42-5). Picking table can be started and stopped from the tractor's control panel (Fig. 42-6).

The picking table is connected to the main bunker by a stay providing end conveyor to automatically when bunker is raised.



Before lifting the bunker the picking table should be cleared of potatoes in order to avoiding potatoes dropping off when picking table end is raised.

The picking web should be stopped while bunker is raised. The end section should not be operated while bunker is raised due to danger of collision (Fig. 42-7).

The end section of the picking table is operated by a joystick on the tractors panel (Fig. 42-8). It is even possible to operate the end from picking table if machine includes electronic controls and picking table control panel*. The end section is automatically raised when bunker lift is operated.

When bunker is empty the end section should be fully lowered. It should be raised according to the volume of potatoes in the bunker. It may cause damage to the crop if the end section is touching the potatoes.

When the end section is fully raised, it should remain in that position till bunker is emptied. Move bunker floor gradually when potatoes get close to the web.

7.10.3 Automatic height adjustment of picking table end section*

Automatic height adjustment ensures constant distance between potatoes and picking table. The function is activated by Key 15 on the panel (Fig. 32-

When the outer end is in top position the automatic function is disengaged. The end should remain in top position until bunker is emptied and lowered fully.

If the machine is equipped with automatic height adjustment only (no automatic bunker floor control) the bunker floor has to be manually operated when the potatoes is touching the picking table end. See chapter 7.12.5.

7.10.4 Grader*

The size of the potatoes are infinitely adjusted from 20 to 50 mm with the bolts A and B (Fig. 44-1).



Ensure that shafts are parallel. Non-parallel shafts will cause excessive wear and damage on gears and bearings.

7.10.5 Extended operators' platform*

The additional platform can be mounted in front of the lefthand main platform. Not available if grader bunker i fitted.

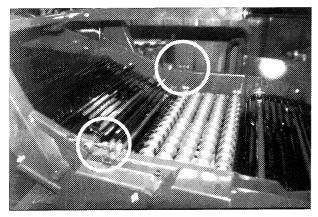
7.10.6 Picking table canopy*

Ensure that moving parts don't tear apart the canvas. The walls can be folded in order to get more fresh air in hot weather. Secure properly in strong wind.

7.10.7 Audible alarm

The alarm is activated by pressing the knob on the picking table (Fig. 44-2). When electronic controls are included even tractor driver can operate the alarm from the control panel.

Driver and operators should agree on communication signals.





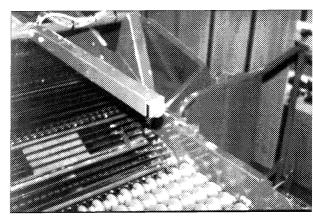


Fig. 44-2

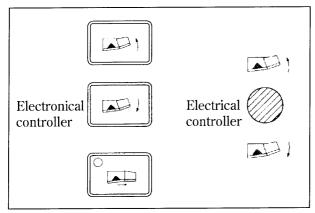


Fig. 44-3

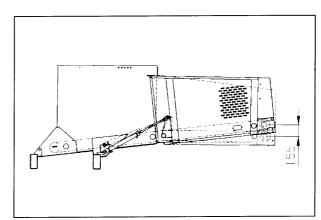


Fig. 44-4

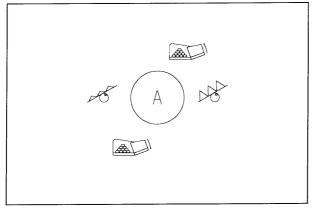


Fig. 44-5

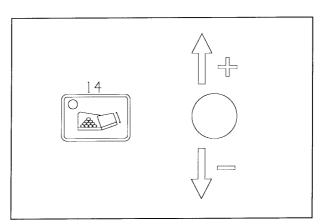


Fig. 44-6

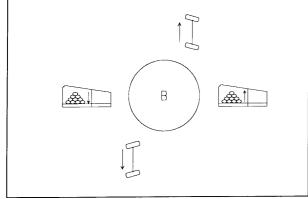


Fig. 44-7

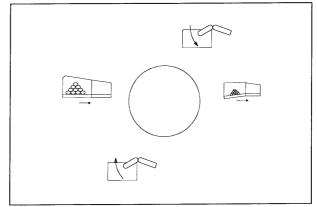


Fig. 44-8

7.11 Grader bunker*

The end section is operated hydraulically from the picking table (Fig. 44-3). It is due to safety not possible to control this from the tractor cab. The moving floor can be operated both from tractor and picking table.

The bunker end must be folded and secured during transport. The lock van be damaged if not removed prior to operating the folding cylinders.

The end section should be in lowered position when harvesting. Two discharge height positions are available by change of cylinders pivot points (Fig. 44-4). Note! When folded from upper discharge position cylinders are not fully pulled in.

When bunker is filled to the top level, floor should be moved gradually.

Increase visibility by raising the main bunker prior to emptying the grader bunker. After discharging, the end section should be folded in if it causes problems when discharging main crop.

The bunker floor canvas can be damaged by sharp objects. The blue canvas strap indicates the chain connectors.

Danger! Make sure that people keeps away from bunker when folding the outer section.

7.12 The main bunker

7.12.1 Operating the bunker

The main bunker is operated from the tractors control panel.

When electric controls are fitted, end section is controlled by joystick A (Fig. 44-5).

When electronic controls are fitted, press key 14 and then operate toggle switch E (Fig. 44-6).

Raise and lower with bunker operating joystick B (Fig. 44-7).

Operate moving floor with joystick D (Fig. 44-8).

During transport the end section shall be secured by the forward wire (Fig. 46-1).

The wire should be in upper position when end is folded out thus carrying the weight of the end section. Assure that wire is properly tensionned.

The bunker floor canvas can be damaged by sharp objects. The blue canvas strap indicates the chain connectors.

Keep away from raised bunker. Put the safety leg into upright position ahead of any work is done underneath the bunker. Discharge bunker ahead of any repair is done.

7.12.2 Filling the main bunker

End section should be in lower position when harvesting. When the end section of the picking table is in the top position the moving floor should be moved in short steps until the bunker is completely filled.

7.12.3 Discharging the main bunker and stability

When bunker is raised the stability is decreased due to the high positioned centre of gravity. The ground surface should level and even in order to avoid danger.

There is a risk of overturning when machine is moving with a raised bunker. Be careful when raising & lowering the bunker or when moving machine with bunker in raised position.

When unloading use following procedure:

- 1. Drawbar to the extreme left.
- 2. Drive close to unloading position.
- 3. Raise bunker when machine is not moving.
- 4. Drive carefully to unloading position and unload the potatoes.
- 5. Don't use jerky movements

Operator's manual Kverneland UN 5300

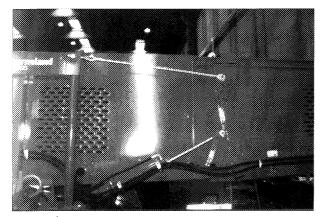


Fig. 46-

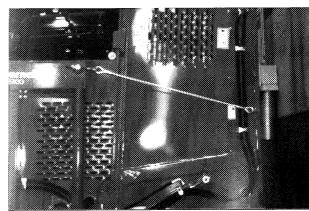


Fig. 46-2

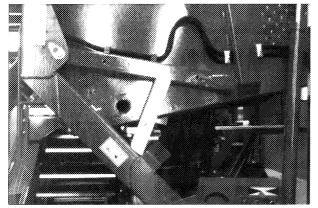


Fig. 46-3

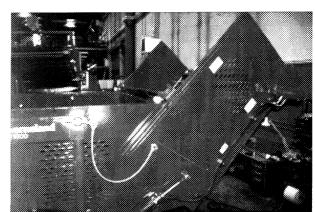


Fig. 46-4

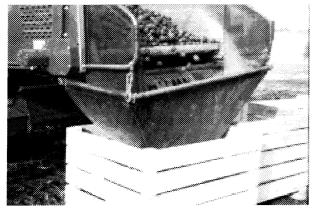


Fig. 46-5

7.12.4 Moving bunker end curtain*

The moving curtain stops potatoes from rolling towards bunker outlet thus increasing the bunker capacity.

Raise the end section to move curtain to inner position (Fig. 46-4).

A slightly raised end section may help to maximise the hopper filling rate. Observe! Lower the end section ahead of any operation of moving floor.

7.12.5 Automatic moving floor controls*

Automatic moving floor controls requires the automatic height adjustment of the picking table end and moving bunker end curtain fitted.

The automatic moving floor controls provide automatic movement of roller floor as the potatoes get close to picking table in top position.

The function is activated by the key 15 on the control panel (Fig. 32-1).

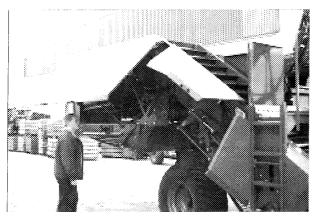
When reaching the stop position, the curtain activates a microswitch disengaging the automatic function. Discharging is operated the ordinary way.

7.12.6 Bunker discharge chute*

When discharging the chute should be lowered into the box or trailer (Fig. 46-5). Quick attachment provides simple dismantling when not in use.

7.13 Bunker canopy*

Ensure that moving parts don't damage the canopy.



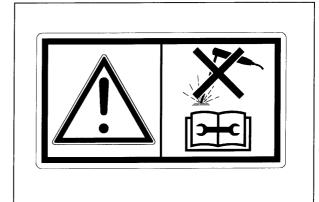
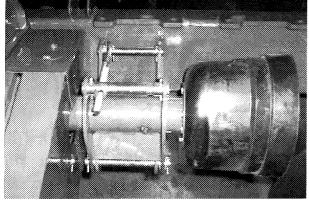


Fig. 48-1 Fig. 48-2



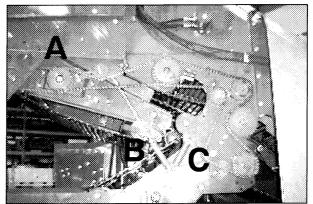
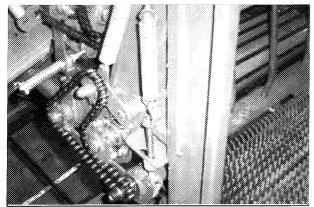


Fig. 48-3 Fig. 48-4



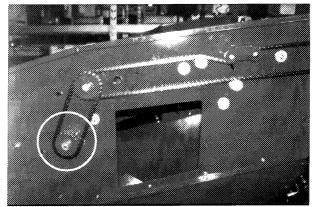
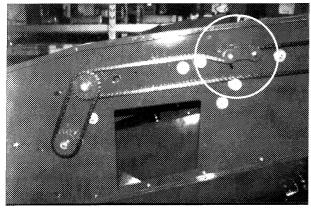


Fig. 48-5 Fig. 48-6



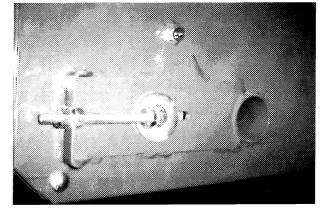


Fig. 48-7 Fig. 48-8

8. Maintenance

8.1 Generally

All side panels at the machines right hand side can be opened to provide simple maintenance and inspection (Fig. 48-1).

8.2 Tyre pressure

3t	4t	4t + grader bunker
320	400	480 kpa
180	(220)	—— kpa
		340 kpa
160	200	(220) kpa
100	140	170 kpa
	320 180 160	320 400 180 (220) 160 200

8.3 Welding on the machine

Disconnect all electronics before start welding. (Fig. 48-2)

8.4 Retensioning bolts

Special attention to bolts for wheels, drawbar and bunker. Check after one hour and thereafter weekly. Use torque 220Nm. Other bolts and nuts should be retensionned after 8 hour and thereafter weekly.

8.5 Chain tensioning

Alternative gear exchange* (Fig. 48-3) Automatic

Main drive unit (Fig. 48-4 C) Automatic

Secondary sieving web (Fig. 48-4 B)

Move sprocket by loosen bolts and moving all bracket A. Tensioning of chain between main drive unit and adjustable bracket is automatic.

Rotating roller secondary sieving web Automatic

Haulm roller (Fig. 48-5)

Automatic

Cross conveyer - hedgehog web

Automatic

Picking table motor (Fig. 48-6)

Automatic

Picking table conveyor end/grader*/cleaning rollers* (Fig. 48-7)

Automatic

Bunker floor (Fig. 48-8)

Tighten each side at machines right hand side. Both sides tightened equally tightened.

8.6 Belt tensioning

Main sieving web

No tensioning. If web channel is not straight: Adjusted with bolt on digging unit's right hand side (Fig. 50-1).

Flight conveyor

Bolt tensioning on lower end rollers, spring loaded tensioner right-hand side (Fig. 50-2).

Haulm diviner web

Automatic

Secondary sieving web

Spring loaded bolts (Fig. 50-3) on each side of the web

Third sieving web

Spring loaded bolts (Fig. 50-3) on each side of the web

Hedgehog web

Bolts for rollers in lefthand end (Fig. 50-4)

Picking table/trash web

Tension bolts in rear end (Fig. 50-5)

Picking table end section

Forward end

Separator deflector web

Tension bolts

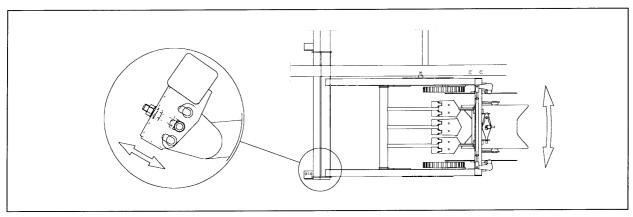


Fig. 50-1

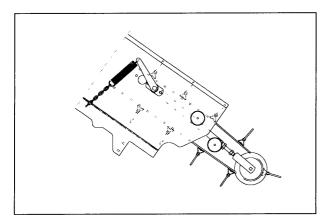


Fig. 50-2

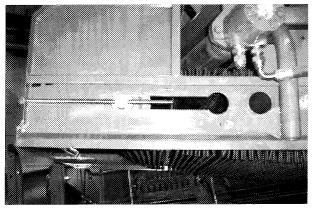


Fig. 50-4

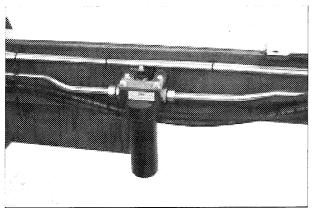


Fig. 50-6

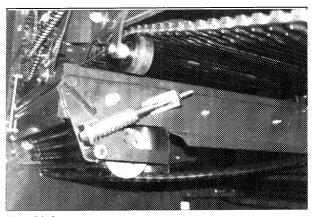


Fig. 50-3

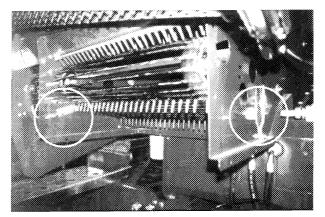


Fig. 50-5

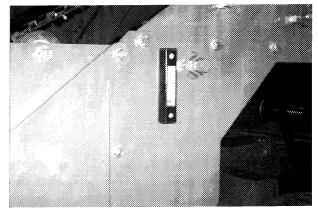


Fig. 50-7

8.7 Lubrication

Lubricate according to lubrication chart section 8.13 and 8.14.

Follow manufacturers recommendations for lubrication or PTO-shaft, universal joints and safety clutches.

8.8 Oil filters

The pressure oil filter for the system operated by the tractor should be changed annually. It is positioned at the left beam of the frame under the bunker (Fig. 50-6). The filter housing has an indicator fitted. If the indicator shows red at normal temperatures, element should be replaced immediately. Use a 25my filter element.

The integrated hydraulic system includes a return filter positioned at the left hand side of the tank (Fig. 50-7). It should be changed annually using a 25my filter element.

Filter type Ordering number

Pressure filter element:

Parker 306685

Return filter element: Return filter 11/4" spin on

Air filter for oil tank 332711

8.9 Change of oil

Hydraulic oil:

Change oil after 200 hours thereafter every 500 hours. Use oil type HD 46. Oil volume approx. 120 litres. Level of oil is measured on the right hand side of the tank (Fig. 50-7). Filling cap close to the filling indicator at the right-hand side of the oil tank.

Gear unit for oil pump:

Change after 200 hours. Type of oil is transmission oil SAE 80/90. Volume of oil 0,34 litre.

Angular gear boxes:

Change oil after 50 hours and thereafter every 500 hours. Type of oil is SAE 90 EP approx. 1,1 litre.

8.10 Hydraulic valve bank

When working in particularly dusty conditions the cap opposite the solenoid should be covered in order to prevent dust penetration (plastics foam). Should be cleaned annually.

8.11 Electronics

The electronics is normally free of maintenance. The driver units is positioned over the valve bank. In order to get easy access to driver units the electronics boxes can be tilted.

8.12 Cleaning and storage

Remove soil and haulm regularly, especially inside webs and in belt crossings. Soil and haulm stuck in the belts channels might block and damage the potatoes.

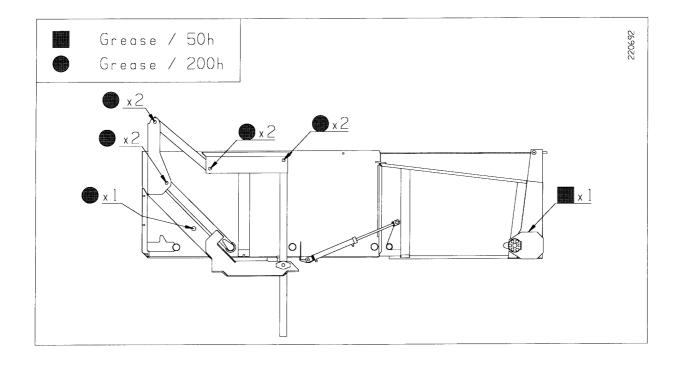
After the season or when the machine by other reasons should be stores for some time do the following:

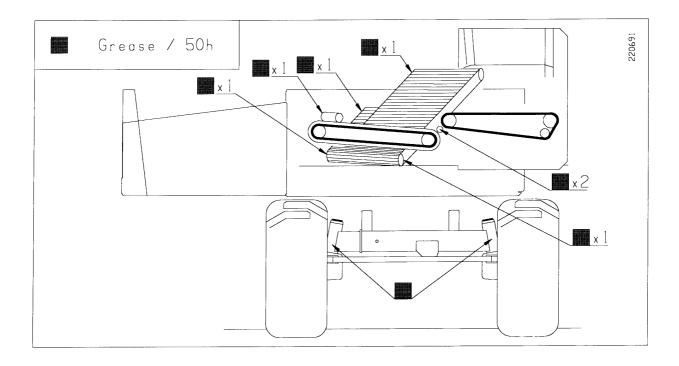
1) Clean the machine properly.

Note! Be careful close to bearings and electronics components when using a high pressure cleaner. Water can penetrate the seals.

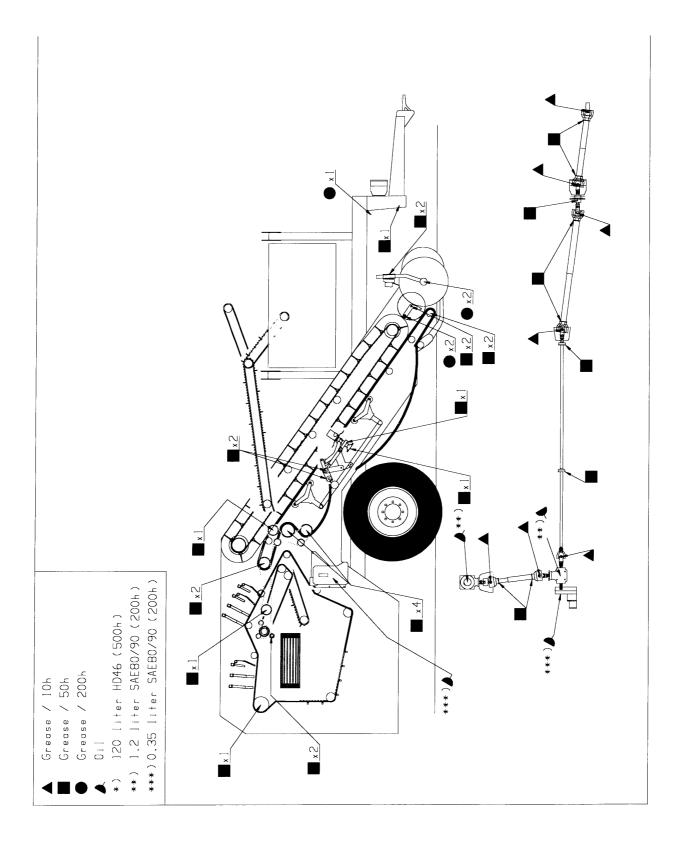
- 2) Check webs, sprockets and chains for damages
- 3) Lubricate according to lubrication chart.
- 4) Repaint if paint damages.
- 5) Store in place protected against rain and snow, sunlight and aggresives.
- 6) Electronic/electric equipment should be disconnected and stored indoor in a tempered room in order to prevent condensation. Don't pull the cords when disconnecting! Treat components carefully and avoid sharp objects
- 7) Check bolts for wear and tear.
- 8) Check tyres and pressure.
- 9) Move drawbar-, steering- and agitation-cylinders in, to keep rod inside. loaded cylinders should be let out and rod lubricated with grease to prevent corrosion.

8.13 Lubrication chart front and behind UN5300





8.14 Lubrication chart right hand side UN5300



9. Trouble shooting

9.1 Mechanics

Problem	Reason / Remedy
Safety couplings trip during operation	Check that webs and rollers are not blocked by
	stones etc.
Main web runs out of line	Adjust the lifting unit with the screw at its right
	hand (wears lifting unit side guards) side.
Main web drive rollers slipping the belt	Remove packed soil in the share unit and objects
	stuck in the web.
Blocking of belt drive	Remove objects/stones in the web.

9.2 Hydraulics

Problem	Reason / Remedy
Hydraulic functions don't work	Check that solenoids are activated
	Swap hoses or turn oil flow
	Check quick-couplers
	Check John Deere screw position (in end plate of the valve bank) (see section. 3.4)
Share raises as soon as pressure is put on	No return to tank, check quick coupler
Hydraulic functions only possible to activate manually	Check voltage - at least 10.8V at the solenoids
	Check polarity, if necessary swap + and
	Make new power supply from the battery with bigger cross-sectional area
	Broken wires, blown fuse or problems in the control panel
Relief valve on tractor opens	Open closed centre screw in the end plate
Steering of tractor moves jerky (John Deere)	Close closed centre screw in the end plate
Adjustment of drawbar slow	High friction in hinge bolt. Lubricate when drawbar is unloaded
Bunker moves slowly down	High return pressure, check couplings between harvester and tractor.
The alarm does not work	Swap cords in command panel connection
	Broken cords

9.3 Electronics

Error message	Reason / Remedy
«Initializing» don't disappear after connection	If message don't disappear after a few seconds, check transmission cable from control panel to driver units at the machine (C and D card)
«Fatal error»	Chip containing parameters or printcard defect
«Memory corrupted»	Contact your Kverneland dealer.
«No data found»	The system is not able to find values from the memory. Contact your Kverneland dealer.
«Invalid data version»	Wrong combination of program versions in operators panel and C and D card.
	Problem with saving or not saving of parameters
	Contact your Kverneland dealer.
«Warning!! Power fail»	Problems with power supply. Check cable.
«Warning!! CAN error» (+C, D, CD or nothing)	Communication problem between detected units,
	If C, D, CD displayed, check data-cable and connections
	If no letter indication, reset failure message with toggleswitch <->.
«Warning!! Emergency stop»	Relay prepared for emergency stop on D-card activated. Contact your Kverneland dealer.
«System mode entered»	The system is in system mode, only for service staff instead of normal. Toggleswitch to <+>. Disconnect and connect power.
«No sensors connected»	Broken cable between sensor and driver box. Check cords for connected sensors.
	The machine is possible to operate without sensors. Automatic functions will not work

9.4 Soil separation

Problem	Reason / Remedy
Soil disappears before leaving the main web (Soil should follow to be gentle to the potatoes)	Reduce the agitation
	Increase flight conveyer speed
	Assemble belt with smaller rod distance
Soil and clods on the picking table	Reduce speed on flight conveyer belt to increase sieving capacity
	Increase agitation
	Reduce share-depth in order to not digging hard layers
Shares does not go down or down to fast.	Adjust soil penetration by changing hinge point on the frame

9.5 Haulm separation

Problem	Reason / Remedy
Haulm sticks to frame for the share.	Increase share angle and raise lifting unit by the diabolo
	Sharpen the roller discs.
Excess of haulm on secondary sieving web and	Fit more additional straps in haulm diviner web cross conveyer
	Reduce haulm diviner web speed
	Change path of web to more straight
Excess of haulm by haulm guides	Remove haulm guides, distribute the rest.
Haulm roller does not separate haulm.	Move haulm roller out

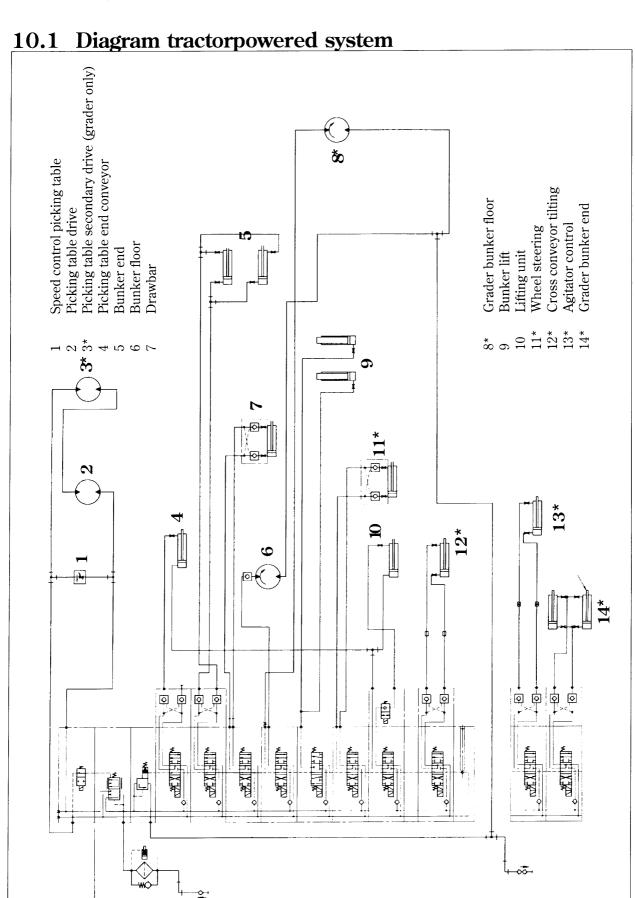
9.6 Loss of potatoes

Problem	Reason / Remedy
Potatoes left in the ground	Adjust the share depth by using the diabolo
Loss of potatoes by roller discs	To big distance between discs and shares
Potatoes falling through web	Use web with smaller spacing or check web for damages
Loss of potatoes by haulm roller	Tension haulm roller springs
	Move haulm roller forward - under web.
	Increase harvester revolutions
	Reduce forward speed
	Use haulm pulverizer

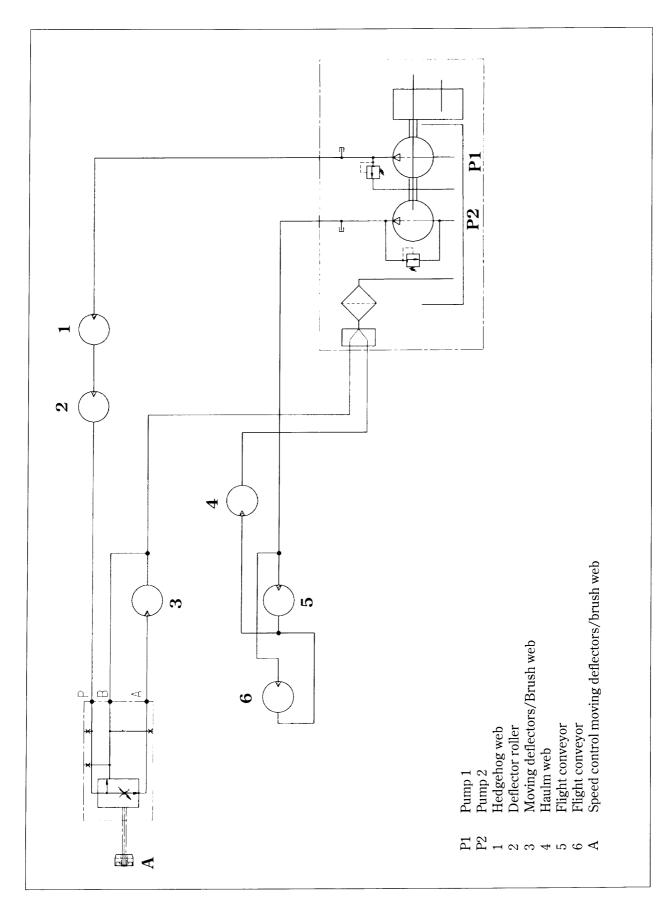
9.7 Damage to the crop

Problem	Reason / Remedy
Potatoes damaged in row	Tyre crushing damages. Use narrow tyres and adjust wheel setting on tractor
Damages caused by the harvester	Too strong agitation
	Web gap to wide
	To high revolutions on the machine
	Forward speed too low
	Share adjustment to shallow
	Roller discs to far in.
	Potatoes squeezed in haulm rollers, rollers should be moved forward and haulm guides turned backward
	Poor climate (cold, wet)
	Stony soil
	To big drop from picking table to bunker. Lower
	outer part of picking table
Damages caused during unload	Big drop from bunker, use bunker chute and lower
-	bunker
	Careless handling of the potatoes

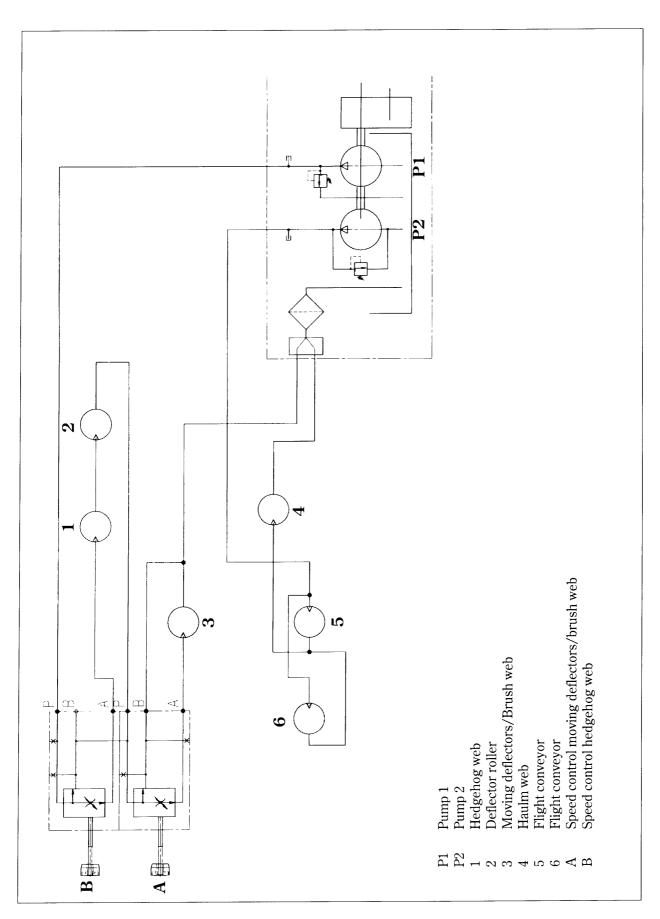
10 Hydraulics and diagram



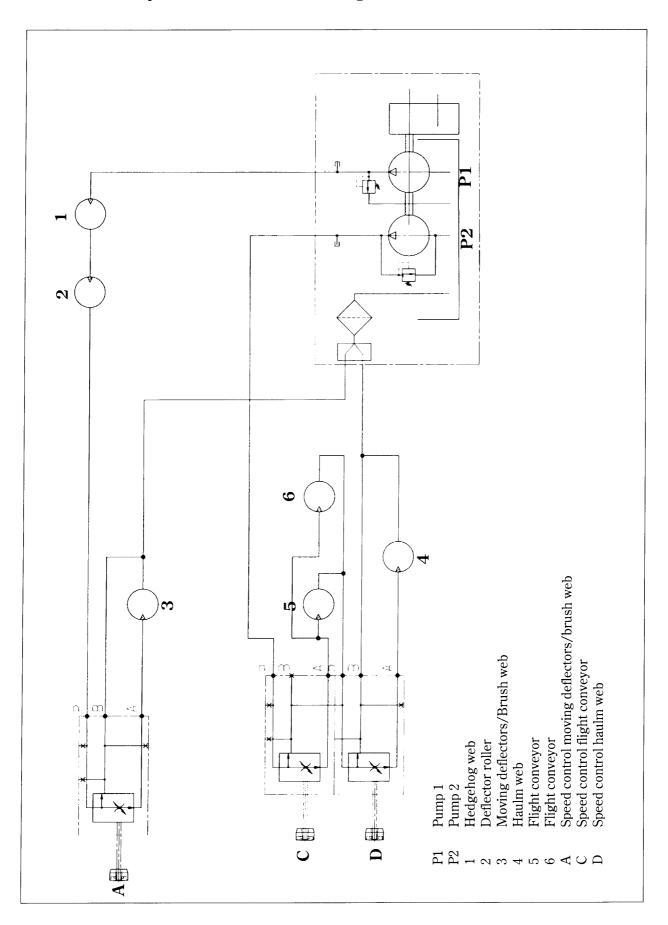
10.2 Diagram pump-powered system



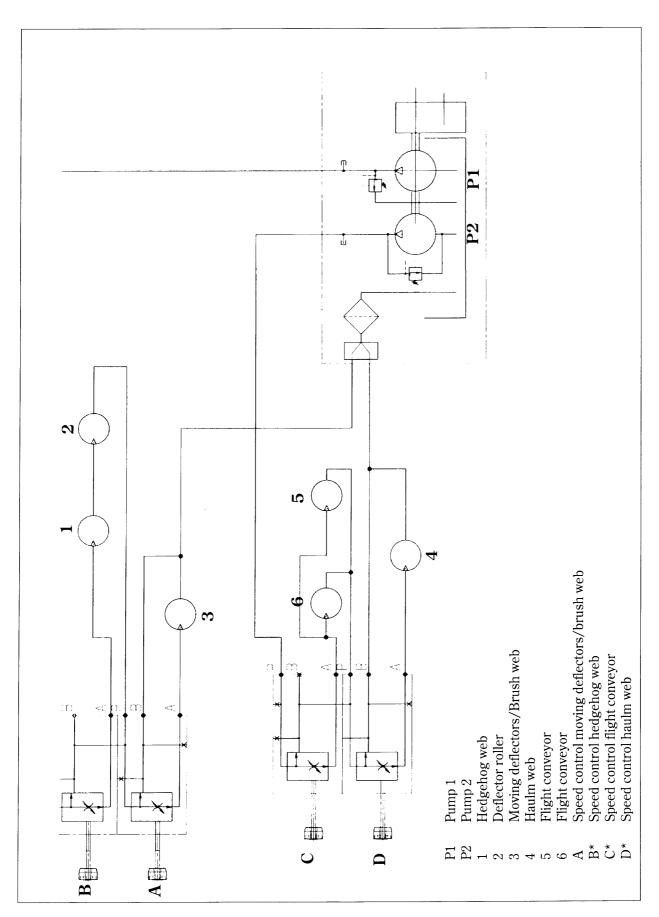
10.3 Diagram pump-powered system with optional hedgehog web speed control



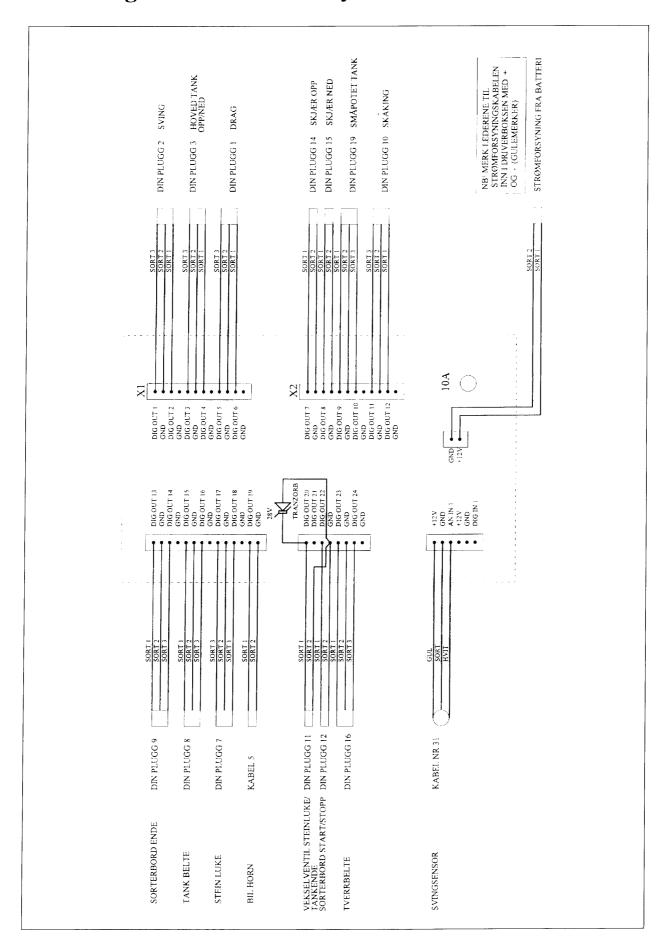
10.4 Diagram pump-powered system with optional flight conveyor and haulm web speed control



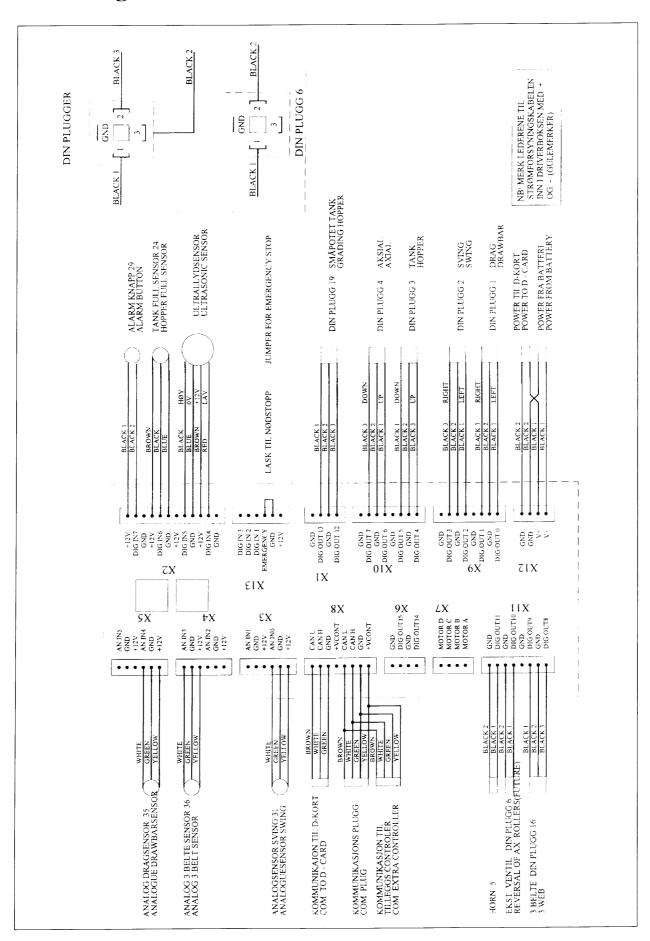
10.5 Diagram pump-powered system with optional flight conveyor, haulm web & hedgehog web speed control



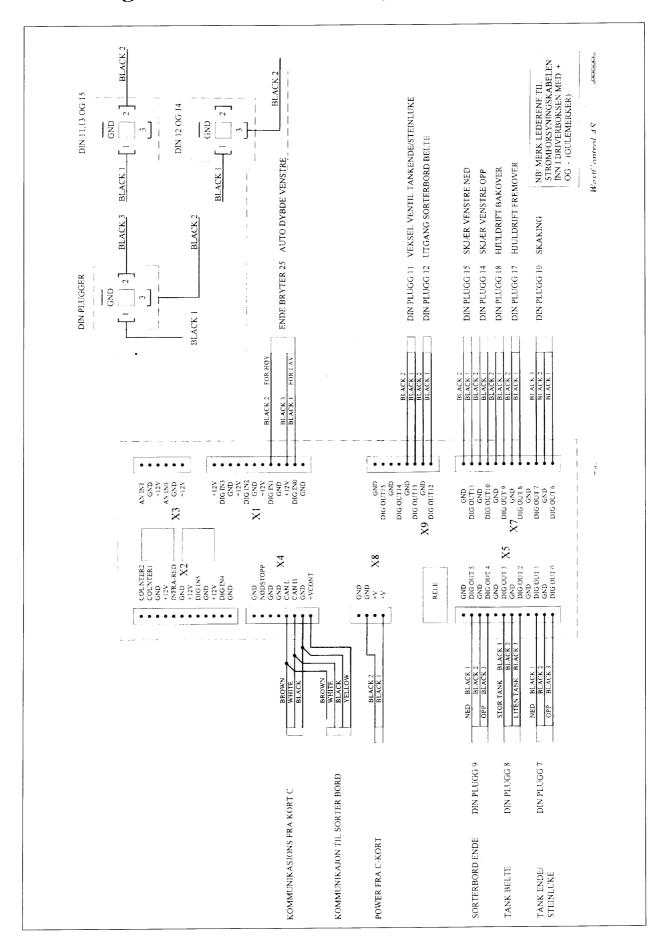
10.6 Diagram electric controlsystem



10.7 Diagram electronical controlsystem C-card



10.8 Diagram electronical controlsystem D-card



Notes
